

Hydrodynamic Limits for the Boltzmann Equation

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LECTURE 6

THE NAVIER-STOKES LIMIT: CONVERGENCE PROOF

Conservation defects $\rightarrow 0$

(as in FG+DL, CPAM 2002, but simpler)

Proposition. $\mathbf{D}_\epsilon(v) \rightarrow 0$ in $L^1_{loc}(\mathbf{R}_+ \times \mathbf{R}^3)$ as $\epsilon \rightarrow 0$.

• Split the conservation defect as $\mathbf{D}_\epsilon(v) = \mathbf{D}_\epsilon^1(v) + \mathbf{D}_\epsilon^2(v)$ with

$$\mathbf{D}_\epsilon^1(v) = \frac{1}{\epsilon^3} \left\langle\left\langle v_{K_\epsilon} \tilde{\gamma}_\epsilon \left(\sqrt{G'_\epsilon G'_{\epsilon*}} - \sqrt{G_\epsilon G_\epsilon} \right)^2 \right\rangle\right\rangle$$

$$\mathbf{D}_\epsilon^2(v) = \frac{2}{\epsilon^3} \left\langle\left\langle v_{K_\epsilon} \tilde{\gamma}_\epsilon \left(\sqrt{G'_\epsilon G'_{\epsilon*}} - \sqrt{G_\epsilon G_\epsilon} \right) \sqrt{G_\epsilon G_\epsilon} \right\rangle\right\rangle$$

That $\mathbf{D}_\epsilon^1(v) \rightarrow 0$ comes from the entropy production estimate.

• Setting $\Xi_\epsilon = \frac{1}{\epsilon^2} \left(\sqrt{G'_\epsilon G'_{\epsilon*}} - \sqrt{G_\epsilon G_\epsilon} \right) \sqrt{G_\epsilon G_\epsilon}$, we further split $\mathbf{D}_\epsilon^2(v)$ into

$$\begin{aligned} \mathbf{D}_\epsilon^2(v) = & -\frac{2}{\epsilon} \left\langle\left\langle v \mathbf{1}_{|v|^2 > K_\epsilon} \hat{\gamma}_\epsilon \Xi_\epsilon \right\rangle\right\rangle + \frac{2}{\epsilon} \left\langle\left\langle v \hat{\gamma}_\epsilon (1 - \hat{\gamma}_{\epsilon*} \hat{\gamma}'_\epsilon \hat{\gamma}_{\epsilon*}) \Xi_\epsilon \right\rangle\right\rangle \\ & + \frac{1}{\epsilon} \left\langle\left\langle (v + v_1) \hat{\gamma}_\epsilon \hat{\gamma}_{\epsilon*} \hat{\gamma}'_\epsilon \hat{\gamma}_{\epsilon*} \Xi_\epsilon \right\rangle\right\rangle \end{aligned}$$

The first and third terms are easily mastered by the entropy production bound and classical estimates on the tail of Gaussian distributions.

• Sending the second term to 0 requires knowing that

$$(1 + |v|) \left(\frac{\sqrt{G_\epsilon} - 1}{\epsilon} \right)^2 \text{ is uniformly integrable on } [0, T] \times K \times \mathbf{R}^3$$

for the measure $dt dx M dv$, for each $T > 0$ and each compact $K \subset \mathbf{R}^3$.

Asymptotic behavior of the momentum flux

Proposition. Denoting by Π the $L^2(Mdv)$ -orthogonal projection on $\ker \mathcal{L}$

$$\mathbf{F}_\epsilon(A) = 2 \left\langle A \left(\Pi \frac{\sqrt{G_\epsilon} - 1}{\epsilon} \right)^2 \right\rangle - 2 \left\langle \hat{A} \frac{1}{\epsilon^2} \mathcal{Q}(\sqrt{G_\epsilon}, \sqrt{G_\epsilon}) \right\rangle + o(1)_{L^1_{loc}(dtdx)}$$

The proof is based upon splitting $\mathbf{F}_\epsilon(A)$ as

$$\mathbf{F}_\epsilon(A) = \left\langle A_{K_\epsilon} \gamma_\epsilon \left(\frac{\sqrt{G_\epsilon} - 1}{\epsilon} \right)^2 \right\rangle + \frac{2}{\epsilon} \left\langle A_{K_\epsilon} \gamma_\epsilon \frac{\sqrt{G_\epsilon} - 1}{\epsilon} \right\rangle$$

using the uniform integrability of $(1 + |v|) \left(\frac{\sqrt{G_\epsilon} - 1}{\epsilon} \right)^2$ and the following consequence thereof

$$\lim_{\epsilon \rightarrow 0} \left\| \frac{\sqrt{G_\epsilon} - 1}{\epsilon} - \Pi \frac{\sqrt{G_\epsilon} - 1}{\epsilon} \right\|_{L^2_{loc}(dtdx; L^2((1+|v|)Mdv))} = 0$$

- By the entropy production estimate, modulo extraction of a subsequence

$$\frac{1}{\epsilon^2} \left(\sqrt{G'_\epsilon G'_{\epsilon^*}} - \sqrt{G_\epsilon G_\epsilon} \right) \rightharpoonup q \text{ in } L^2(dt dx d\mu)$$

and passing to the limit in the scaled, renormalized Boltzmann equation leads to

$$\iint_{\mathbf{R}^3 \times \mathbf{S}^2} q |(v - v_*) \cdot \omega| M_* dv_* d\omega = \frac{1}{2} v \cdot \nabla_x g = \frac{1}{2} A : \nabla_x u + \text{odd in } v$$

- Since $\frac{\sqrt{G_\epsilon} - 1}{\epsilon} \simeq \frac{1}{2} g_\epsilon \gamma_\epsilon$, one gets

$$\mathbf{F}_\epsilon(A) = A(\langle v_{K_\epsilon} g_\epsilon \gamma_\epsilon \rangle) - \nu(\nabla_x u + (\nabla_x u)^T) + o(1)_{w-L^1_{loc}(dt dx)}$$

(remember that $A(u) = u \otimes u - \frac{1}{3}|u|^2 I$), while

$$\langle v_{K_\epsilon} g_\epsilon \gamma_\epsilon \rangle \rightharpoonup u \text{ in } L^1_{loc}(\mathbf{R}_+ \times \mathbf{R}^3)$$

Strong compactness

• In order to pass to the limit in the quadratic term $A(\langle v_{K_\epsilon} g_\epsilon \gamma_\epsilon \rangle)$, one needs **strong- L^2 compactness of $\langle v_{K_\epsilon} g_\epsilon \gamma_\epsilon \rangle$** .

• Velocity averaging provides strong compactness **in the x -variable**:

$$\left(\frac{\sqrt{\epsilon^\alpha + G_\epsilon} - 1}{\epsilon} \right)^2 \text{ is locally uniformly integrable on } \mathbf{R}_+ \times \mathbf{R}^3 \times \mathbf{R}^3$$
$$(\epsilon \partial_t + v \cdot \nabla_x) \frac{\sqrt{\epsilon^\alpha + G_\epsilon} - 1}{\epsilon} \text{ is bounded in } L^1_{loc}(\mathbf{R}_+ \times \mathbf{R}^3 \times \mathbf{R}^3)$$

This implies that, for each $T > 0$ and each compact $C \subset \mathbf{R}^3$,

$$\int_0^T \int_C |\langle v_{K_\epsilon} g_\epsilon \gamma_\epsilon \rangle(t, x + y) - \langle v_{K_\epsilon} g_\epsilon \gamma_\epsilon \rangle(t, x)|^2 dx dt \rightarrow 0$$

as $|y| \rightarrow 0$, uniformly in $\epsilon > 0$

- It remains to get compactness in the time variable. Observe that

$\partial_t P \langle v_{K_\epsilon} g_\epsilon \gamma_\epsilon \rangle = P(\mathbf{D}_\epsilon(v) - \operatorname{div}_x \mathbf{F}_\epsilon(A))$ is bounded in $L^1_{loc}(dt, W^{-s,1}_{x,loc})$

(Recall that $\mathbf{D}_\epsilon(v) \rightarrow 0$ while $\mathbf{F}_\epsilon(A)$ is bounded in $L^1_{loc}(dtdx)$).

- Together with the compactness in the x -variable that follows from velocity averaging, this implies that

$$P \langle v_{K_\epsilon} g_\epsilon \gamma_\epsilon \rangle \rightarrow u \text{ in } L^2_{loc}(dtdx)$$

- Recall that $\langle v_{K_\epsilon} g_\epsilon \gamma_\epsilon \rangle \rightarrow u$ in $L^2_{loc}(dtdx)$; we DO NOT seek to prove that

$$\langle v_{K_\epsilon} g_\epsilon \gamma_\epsilon \rangle \rightarrow u \text{ strongly in } L^2_{loc}(dtdx)$$

Filtering acoustic waves (PLL+NM, ARMA 2002)

- Instead, we prove that

$$P \operatorname{div}_x \left(\langle v_{K_\epsilon} g_\epsilon \gamma_\epsilon \rangle^{\otimes 2} \right) \rightarrow P \operatorname{div}_x \left(u^{\otimes 2} \right) \text{ in } \mathcal{D}'(\mathbf{R}_+^* \times \mathbf{R}^3) \text{ as } \epsilon \rightarrow 0$$

- Observe that

$$\epsilon \partial_t \langle v_{K_\epsilon} g_\epsilon \gamma_\epsilon \rangle + \nabla_x \langle \frac{1}{3} |v|_{K_\epsilon}^2 g_\epsilon \gamma_\epsilon \rangle \rightarrow 0 \text{ in } L_{loc}^1(\mathbf{R}_+; W_{loc}^{-1,1}(\mathbf{R}^3))$$

$$\epsilon \partial_t \langle \frac{1}{3} |v|_{K_\epsilon}^2 g_\epsilon \gamma_\epsilon \rangle + \operatorname{div}_x \langle \frac{5}{3} v_{K_\epsilon} g_\epsilon \gamma_\epsilon \rangle \rightarrow 0 \text{ in } L_{loc}^1(\mathbf{R}_+; W_{loc}^{-1,1}(\mathbf{R}^3))$$

as $\epsilon \rightarrow 0$.

- Setting $\nabla_x \pi_\epsilon = (I - P) \langle v_{K_\epsilon} g_\epsilon \gamma_\epsilon \rangle$, the system above becomes

$$\epsilon \partial_t \nabla_x \pi_\epsilon + \nabla_x \langle \frac{1}{3} |v|_{K_\epsilon}^2 g_\epsilon \gamma_\epsilon \rangle \rightarrow 0 \text{ in } L_{loc}^1(\mathbf{R}_+; W_{loc}^{-s,1}(\mathbf{R}^3)), \quad s > 1$$

$$\epsilon \partial_t \langle \frac{1}{3} |v|_{K_\epsilon}^2 g_\epsilon \gamma_\epsilon \rangle + \frac{5}{3} \Delta_x \pi_\epsilon \rightarrow 0 \text{ in } L_{loc}^1(\mathbf{R}_+; W_{loc}^{-1,1}(\mathbf{R}^3))$$

- Straightforward computation shows that

$$\operatorname{div}_x \left((\nabla_x \pi_\epsilon)^{\otimes 2} \right) = \frac{1}{2} \nabla_x \left(|\nabla_x \pi_\epsilon|^2 - \frac{3}{5} \langle \frac{1}{3} |v|_{K_\epsilon}^2 g_\epsilon \gamma_\epsilon \rangle^2 \right) + o(1)_{L^1_{loc}(dtdx)}$$

- On the other hand, because the limiting velocity field is divergence-free, one has

$$\nabla_x \pi_\epsilon \rightharpoonup 0 \text{ in } L^2_{loc}(dtdx) \text{ as } \epsilon \rightarrow 0$$

- Splitting

$$\begin{aligned} P \operatorname{div}_x \left(\langle v_{K_\epsilon} g_\epsilon \gamma_\epsilon \rangle^{\otimes 2} \right) &= P \operatorname{div}_x \left((P \langle v_{K_\epsilon} g_\epsilon \gamma_\epsilon \rangle)^{\otimes 2} \right) + P \operatorname{div}_x \left((\nabla_x \pi_\epsilon)^{\otimes 2} \right) \\ &\quad + 2P \operatorname{div}_x \left(P \langle v_{K_\epsilon} g_\epsilon \gamma_\epsilon \rangle \vee \nabla_x \pi_\epsilon \right) \end{aligned}$$

The last two terms vanish with ϵ while the first converges to $P \operatorname{div}_x (u^{\otimes 2})$ since $P \langle v_{K_\epsilon} g_\epsilon \gamma_\epsilon \rangle \rightarrow u$ **strongly** in $L^2_{loc}(dtdx)$.

The key estimates (as in FG+LSR, Invent. Math. 2004)

Proposition. For each $T > 0$ and each compact $K \subset \mathbb{R}^3$, the family $\left(\frac{\sqrt{G_\epsilon}-1}{\epsilon}\right)^2 (1 + |v|)$ is uniformly integrable on $[0, T] \times K \times \mathbb{R}^3$ for the measure $dt dx M dv$.

Idea no. 1 We first prove that $\left(\frac{\sqrt{G_\epsilon}-1}{\epsilon}\right)^2 (1 + |v|)$ is uniformly integrable on $[0, T] \times K \times \mathbb{R}^3$ for the measure $dt dx M dv$ **in the v -variable** .

• We say that $\phi_\epsilon \equiv \phi_\epsilon(x, y) \in L^1_{x,y}(d\mu(x)d\nu(y))$ is uniformly integrable **in the y -variable** for the measure $d\mu(x)d\nu(y)$ iff

$$\int \sup_{\nu(A) < \alpha} \int_A |\phi_\epsilon(x, y)| d\nu(y) d\mu(x) \rightarrow 0 \text{ as } \alpha \rightarrow 0 \text{ uniformly in } \epsilon$$

• Start from the formula

$$\mathcal{L} \left(\frac{\sqrt{G_\epsilon} - 1}{\epsilon} \right) = \epsilon Q \left(\frac{\sqrt{G_\epsilon} - 1}{\epsilon}, \frac{\sqrt{G_\epsilon} - 1}{\epsilon} \right) - \frac{1}{\epsilon} Q \left(\sqrt{G_\epsilon}, \sqrt{G_\epsilon} \right)$$

and use the following estimate (G.-Perthame-Sulem, ARMA 1988)

$$\|Q(f, f)\|_{L^2((1+|v|)^{-1}Mdv)} \leq C \|f\|_{L^2(Mdv)} \|f\|_{L^2((1+|v|)Mdv)}$$

to arrive at

$$\begin{aligned} \left(1 - O(\epsilon) \left\| \frac{\sqrt{G_\epsilon} - 1}{\epsilon} \right\|_{L^2(Mdv)} \right) & \left\| \frac{\sqrt{G_\epsilon} - 1}{\epsilon} - \prod \frac{\sqrt{G_\epsilon} - 1}{\epsilon} \right\|_{L^2((1+|v|)Mdv)} \\ & \leq O(\epsilon)_{L^2_{t,x}} + O(\epsilon) \left\| \frac{\sqrt{G_\epsilon} - 1}{\epsilon} \right\|_{L^2(Mdv)}^2 \end{aligned}$$

• This estimates tells us that $\frac{\sqrt{G_\epsilon} - 1}{\epsilon}$ stays close to its associated infinitesimal Maxwellian \Rightarrow regularity+decay in v .

Idea no. 2 Use a L^1 -variant of velocity averaging (FG+LSR, CRAS 2002).

Lemma. *Let $f_n \equiv f_n(x, v)$ be a bounded sequence in $L^1_{loc}(dx dv)$ such that $v \cdot \nabla_x f_n$ is also bounded in $L^1_{loc}(dx dv)$. Assume that f_n is locally uniformly integrable in v . Then*

- f_n is locally uniformly integrable (in x, v), and
- for each test function $\phi \in L^\infty_{comp}(\mathbf{R}_v^D)$, the sequence of averages

$$\rho_n^\phi(x) = \int f_n(x, v) \phi(v) dv$$

is relatively compact in $L^1_{loc}(dx)$.

•Let's prove that the sequence of averages ρ_n^ϕ is locally uniformly integrable (LSR, CPDEs 2002). WLOG, assume that f_n and $\phi \geq 0$.

•Let $\chi \equiv \chi(t, x, v)$ be the solution to

$$\partial_t \chi + v \cdot \nabla_x \chi = 0, \quad \chi(0, x, v) = \mathbf{1}_A(x)$$

Clearly, $\chi(t, x, v) = \mathbf{1}_{A_x(t)}(v)$ (χ takes the values 0 and 1 only). On the other hand,

$$|A_x(t)| = \int \chi(t, x, v) dv = \int \mathbf{1}_A(x - tv) dv = \frac{|A|}{tD}$$

•Remark: this is the basic dispersion estimate for the free transport equation.

•Set

$$g_n(x, v) := f_n(x, v)\phi(v), \text{ and}$$

$$h_n(x, v) := v \cdot \nabla_x g_n(x, v) = \phi(v)(v \cdot \nabla_x f_n(x, v))$$

Both g_n and h_n are bounded in $L^1_{x,v}$, while g_n is uniformly integrable in v .

•Observe that (hint: integrate by parts the 2nd integral in the r.h.s.)

$$\int_A \int g_n dv dx = \int \int_{A_x(t)} g_n dv dx - \int_0^t \iint h_n(x, v) \chi(s, x, v) dx dv ds$$

The second integral on the r.h.s. is $O(t) \sup \|h_n\|_{L^1_{x,v}} < \epsilon$ by choosing $t > 0$ small enough. For that value of t , $|A_x(t)| \rightarrow 0$ as $|A| \rightarrow 0$, hence the first integral on the r.h.s. vanishes by uniform integrability in v .