

Hydrodynamic Limits for the Boltzmann Equation

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LECTURE 2

FORMAL INCOMPRESSIBLE HYDRODYNAMIC LIMITS

Dimensionless form of the Boltzmann equation

- Choose macroscopic scales of time T and length L , and a reference temperature Θ ; this defines 2 velocity scales:

$$V = \frac{L}{T} \text{ (macroscopic velocity) , \quad and } c = \sqrt{\Theta} \text{ (thermal speed)}$$

Finally, set \mathcal{N} to be the total number of particles.

- Define dimensionless time, position, and velocity variables by

$$\hat{t} = \frac{t}{T}, \quad \hat{x} = \frac{x}{L}, \quad \hat{v} = \frac{v}{c}$$

and a dimensionless number density

$$\hat{F}(\hat{t}, \hat{x}, \hat{v}) = \frac{L^3 c^3}{\mathcal{N}} F(t, x, v)$$

- One finds that

$$\frac{L}{cT} \partial_{\hat{t}} \hat{F} + \hat{v} \cdot \nabla_{\hat{x}} \hat{F} = \frac{\mathcal{N}r^2}{L^2} \iint (\hat{F}' \hat{F}'_* - \hat{F} \hat{F}'_*) |(\hat{v} - \hat{v}_*) \cdot \omega| d\omega d\hat{v}_*$$

- The pre-factor multiplying the collision integral is

$$L \times \frac{\mathcal{N}r^2}{L^3} = \frac{L}{\pi \times \text{mean free path}} = \frac{1}{\pi \text{Kn}}$$

- The pre-factor multiplying the time derivative is

$$\frac{\frac{1}{T} \times L}{c} = \text{St}, \quad (\text{kinetic Strouhal number})$$

$$\text{St} \partial_{\hat{t}} \hat{F} + \hat{v} \cdot \nabla_{\hat{x}} \hat{F} = \frac{1}{\pi \text{Kn}} \iint_{\mathbf{R}^3 \times \mathbf{S}^2} (\hat{F}' \hat{F}'_* - \hat{F} \hat{F}'_*) |(\hat{v} - \hat{v}_*) \cdot \omega| d\omega d\hat{v}_*$$

Compressible Euler scaling

- This limit corresponds to $\text{St} = 1$ and $\pi \text{Kn} =: \epsilon \ll 1$, leading to the singular perturbation problem

$$\partial_t F_\epsilon + v \cdot \nabla_x F_\epsilon = \frac{1}{\epsilon} \mathcal{B}(F_\epsilon, F_\epsilon) = \frac{1}{\epsilon} \iint (F'_\epsilon F'_{\epsilon*} - F_\epsilon F_{\epsilon*}) |(v - v_*) \cdot \omega| d\omega dv_*$$

- One expects that, as $\epsilon \rightarrow 0$, $F_\epsilon \rightarrow F$ and $\mathcal{B}(F_\epsilon, F_\epsilon) \rightarrow \mathcal{B}(F, F) = 0$; hence $F(t, x, \cdot)$ is a Maxwellian for all (t, x) , i.e.

$$F(t, x, v) = \mathcal{M}_{(\rho(t,x), u(t,x), \theta(t,x))}(v) = \frac{\rho(t, x)}{(2\pi\theta(t, x))^{3/2}} e^{-\frac{|v-u(t,x)|^2}{2\theta(t,x)}}$$

In other words, F is a **local Maxwellian equilibrium**.

- Problem: to find the governing equations for $\rho(t, x)$, $u(t, x)$ and $\theta(t, x)$.

Formal Euler limit by the moment method

- Let $F^{in} = \mathcal{M}_{(\rho^{in}, u^{in}, \theta^{in})}$ be such that $H(F^{in}|M) < +\infty$; let F_ϵ be a renormalized solution relative to $M = \mathcal{M}_{(1,0,1)}$ of the Boltzmann equation in the compressible Euler scaling

$$St = 1, \text{ and } \pi Kn = \epsilon$$

- Assume that F_ϵ satisfies the local conservation laws of momentum and energy and the local H Theorem, and that

$$F_\epsilon \rightarrow F \text{ a.e., in } L_{loc}^1(dt dx; L^1((1 + |v|^3)dv)) \text{ as } \epsilon \rightarrow 0 \\ \text{and in } L \ln L_{loc}(dt dx; L \ln L((1 + |v|)dv))$$

Theorem. (C. Bardos-F.G. C.R. Acad. Sci. 1984) Then $F = \mathcal{M}_{(\rho,u,\theta)}$, where (ρ, u, θ) is an entropic solution to the compressible Euler system for perfect gases with $(\rho, u, \theta)|_{t=0} = (\rho^{in}, u^{in}, \theta^{in})$

Proof:

•Step 1: The H Theorem implies that F is a **local Maxwellian** i.e. is of the form $F(t, x, v) = \mathcal{M}_{(\rho(t,x), u(t,x), \theta(t,x))}(v)$: indeed

$$\int_0^{+\infty} \iint \mathcal{B}(F_\epsilon, F_\epsilon) \ln F_\epsilon dv dx dt \leq \epsilon H(F^{in} | M) \rightarrow 0$$

as $\epsilon \rightarrow 0$; hence, by Fatou's lemma

$$\int_0^{+\infty} \iint \mathcal{B}(F, F) \ln F dv dx dt = 0$$

• Step 2: Passing to the limit in the local conservation laws + the entropy differential inequality leads to the system of conservation laws for (ρ, u, θ) with entropy condition

$$\begin{aligned}\partial_t \int_{\mathbf{R}^3} \mathcal{M}_{(\rho, u, \theta)} dv + \operatorname{div}_x \int_{\mathbf{R}^3} v \mathcal{M}_{(\rho, u, \theta)} dv &= 0 \\ \partial_t \int_{\mathbf{R}^3} v \mathcal{M}_{(\rho, u, \theta)} dv + \operatorname{div}_x \int_{\mathbf{R}^3} v^{\otimes 2} \mathcal{M}_{(\rho, u, \theta)} dv &= 0 \\ \partial_t \int_{\mathbf{R}^3} \frac{1}{2} |v|^2 \mathcal{M}_{(\rho, u, \theta)} dv + \operatorname{div}_x \int_{\mathbf{R}^3} v \frac{1}{2} |v|^2 \mathcal{M}_{(\rho, u, \theta)} dv &= 0\end{aligned}$$

as well as the differential inequality

$$\partial_t \int_{\mathbf{R}^3} \mathcal{M}_{(\rho, u, \theta)} \ln \mathcal{M}_{(\rho, u, \theta)} dv + \operatorname{div}_x \int_{\mathbf{R}^3} v \mathcal{M}_{(\rho, u, \theta)} \ln \mathcal{M}_{(\rho, u, \theta)} dv \leq 0$$

- The following formulas for the moments of a Maxwellian

$$\int \mathcal{M}_{(\rho,u,\theta)} dv = \rho, \quad \int v \mathcal{M}_{(\rho,u,\theta)} dv = \rho u,$$

$$\int v^{\otimes 2} \mathcal{M}_{(\rho,u,\theta)} dv = \rho(u^{\otimes 2} + \theta I), \quad \int \frac{1}{2}|v|^2 \mathcal{M}_{(\rho,u,\theta)} dv = \frac{1}{2}\rho(|u|^2 + 3\theta)$$

$$\int v \frac{1}{2}|v|^2 \mathcal{M}_{(\rho,u,\theta)} dv = \frac{1}{2}\rho u(|u|^2 + 5\theta)$$

and for its entropy and entropy flux

$$\int \mathcal{M}_{(\rho,u,\theta)} \ln \mathcal{M}_{(\rho,u,\theta)} dv = \rho \ln \left(\frac{\rho}{(2\pi\theta)^{3/2}} \right) - \frac{3}{2}\rho$$

$$\int v \mathcal{M}_{(\rho,u,\theta)} \ln \mathcal{M}_{(\rho,u,\theta)} dv = \rho u \ln \left(\frac{\rho}{(2\pi\theta)^{3/2}} \right) - \frac{3}{2}\rho u$$

show that (ρ, u, θ) is an admissible (entropic) solution of Euler's system.

The incompressible Navier-Stokes limit

- This limit holds under the scaling assumption on the Boltzmann equation

$$St = \pi Kn = \epsilon \ll 1$$

- Moreover, the number density should correspond to a flow with small Mach number

$$Ma = \epsilon$$

Example: $F_\epsilon(t, x, v) = \mathcal{M}_{(1, \epsilon u(t, x), 1)}(v)$

- More generally, the number density should be a fluctuation of order ϵ about a uniform Maxwellian state

$$F_\epsilon(t, x, v) = \mathcal{M}_{(1, 0, 1)}(v) + \epsilon f(t, x, v)$$

Formal derivation of the incompressible Navier-Stokes equations

following a **moment method** due to C. Bardos-F.G.-D. Levermore (C.R. Acad. Sci. 1988)

- Introduce the **relative number density fluctuation** g_ϵ :

$$g_\epsilon(t, x, v) = \frac{F_\epsilon(t, x, v) - M(v)}{\epsilon M(v)}, \quad \text{where } M(v) = \frac{1}{(2\pi)^{3/2}} e^{-\frac{|v|^2}{2}}$$

- In terms of g_ϵ , the Boltzmann equation becomes

$$\epsilon \partial_t g_\epsilon + v \cdot \nabla_x g_\epsilon + \frac{1}{\epsilon} \mathcal{L} g_\epsilon = \mathcal{Q}(g_\epsilon, g_\epsilon)$$

where the **linearized collision operator** \mathcal{L} and \mathcal{Q} are defined by

$$\mathcal{L}g = -2M^{-1}\mathcal{B}(M, Mg), \quad \mathcal{Q}(g, g) = M^{-1}\mathcal{B}(Mg, Mg)$$

Lemma. (Hilbert, Math. Ann. 1912) *The operator \mathcal{L} is self-adjoint, Fredholm, unbounded on $L^2(\mathbb{R}^3; M dv)$ with domain $L^2(\mathbb{R}^3; (1 + |v|)M dv)$ and nullspace $\ker \mathcal{L} = \text{span}\{1, v_1, v_2, v_3, |v|^2\}$*

1. Asymptotic fluctuations

- Multiplying the Boltzmann equation by ϵ and letting $\epsilon \rightarrow 0$ suggests that

$$g_\epsilon \rightarrow g \quad \text{with } \mathcal{L}g = 0$$

By Hilbert's lemma, g is **an infinitesimal Maxwellian**, i.e. is of the form

$$g(t, x, v) = \rho(t, x) + u(t, x) \cdot v + \frac{1}{2}\theta(t, x)(|v|^2 - 3)$$

Notice that g is parametrized by its own moments, since

$$\rho = \langle g \rangle, \quad u = \langle vg \rangle, \quad \text{and } \theta = \langle (\frac{1}{3}|v|^2 - 1)g \rangle$$

• NOTATION:

$$\langle \phi \rangle = \int_{\mathbf{R}^3} \phi(v) M(v) dv$$

2. Local conservation laws

• The continuity equation (local conservation of mass) reads

$$\epsilon \partial_t \langle g_\epsilon \rangle + \operatorname{div}_x \langle vg_\epsilon \rangle = 0, \quad \text{and thus } \operatorname{div}_x \langle vg \rangle = \operatorname{div}_x u = 0$$

which is the **incompressibility condition** in the Navier-Stokes equations.

- The local conservation of momentum takes the form

$$\epsilon \partial_t \langle v g_\epsilon \rangle + \operatorname{div}_x \langle v \otimes v g_\epsilon \rangle = 0$$

Recall the incompressible Navier-Stokes motion equation

$$\partial_t u + u \cdot \nabla_x u - \nu \Delta_x u = -\nabla_x p$$

that involves the term $\nabla_x p$ as the **Lagrange multiplier** associated to the **constraint** $\operatorname{div}_x u = 0$. Accordingly, split

$$v \otimes v = \left(v \otimes v - \frac{1}{3} |v|^2 I \right) + \frac{1}{3} |v|^2 I$$

so that the local conservation of momentum is recast as

$$\epsilon \partial_t \langle v g_\epsilon \rangle + \operatorname{div}_x \langle A g_\epsilon \rangle + \nabla_x \langle \frac{1}{3} |v|^2 g_\epsilon \rangle = 0$$

where

$$A(v) = v \otimes v - \frac{1}{3} |v|^2 I; \text{ notice that } A \perp \ker \mathcal{L}$$

- Passing to the limit in the local conservation of momentum above:

$$\operatorname{div}_x \langle Ag \rangle + \nabla_x \langle \frac{1}{3} |v|^2 g \rangle = 0$$

where g is a local Maxwellian:

$$g(t, x, v) = \rho(t, x) + u(t, x) \cdot v + \theta(t, x) \frac{1}{2} (|v|^2 - 3)$$

In other words, $g(t, x, \cdot) \in \ker \mathcal{L}$ so that

$$\langle Ag \rangle = 0, \quad \text{and thus } \nabla_x \langle \frac{1}{3} |v|^2 g \rangle = \nabla_x (\rho + \theta) = 0$$

If $g \in L^\infty(\mathbf{R}_+; L^2(\mathbf{R}^3; M dv dx))$, this entails the **Boussinesq relation**

$$\rho + \theta = 0, \quad \text{so that } g(t, x, v) = u(t, x) \cdot v + \theta(t, x) \frac{1}{2} (|v|^2 - 5)$$

- It remains to derive the Navier-Stokes motion equation. Start from the local conservation of momentum in the form

$$\partial_t \langle v g_\epsilon \rangle + \operatorname{div}_x \frac{1}{\epsilon} \langle A g_\epsilon \rangle + \nabla_x \frac{1}{\epsilon} \langle \frac{1}{3} |v|^2 g_\epsilon \rangle = 0$$

- Fredholm's alternative $\Rightarrow A = \mathcal{L} \hat{A}$ for some $\hat{A} \perp \ker \mathcal{L}$; thus

$$\begin{aligned} \frac{1}{\epsilon} \langle A g_\epsilon \rangle &= \left\langle \hat{A} \frac{1}{\epsilon} \mathcal{L} g_\epsilon \right\rangle = \langle \hat{A} Q(g_\epsilon, g_\epsilon) \rangle - \langle \hat{A} (\epsilon \partial_t + v \cdot \nabla_x) g_\epsilon \rangle \\ &\rightarrow \langle \hat{A} Q(g, g) \rangle - \langle \hat{A} v \cdot \nabla_x g \rangle \end{aligned}$$

- Since g is an infinitesimal Maxwellian, using the incompressibility condition and Boussinesq's relation shows that

$$\begin{aligned} \langle \hat{A} v \cdot \nabla_x g \rangle &= \frac{1}{2} \langle \hat{A} \otimes A \rangle : D(u) + \langle \hat{A} \otimes \frac{1}{2} (|v|^2 - 3)v \rangle \cdot \nabla_x \theta \\ &= \frac{1}{2} \langle \hat{A} \otimes A \rangle : D(u) \text{ since } \hat{A} \text{ is even} \end{aligned}$$

where $D(u) = \nabla_x u + (\nabla_x u)^T$ is the deformation tensor of u .

Lemma. For each $g \in \ker \mathcal{L}$, one has $\mathcal{Q}(g, g) = \frac{1}{2}\mathcal{L}(g^2)$

Proof: Differentiate twice the relation $\mathcal{B}(\mathcal{M}_{(\rho, u, \theta)}, \mathcal{M}_{(\rho, u, \theta)}) = 0$.

• Hence one has

$$\langle \hat{A}\mathcal{Q}(g, g) \rangle = \frac{1}{2}\langle \hat{A}\mathcal{L}(g^2) \rangle = \frac{1}{2}\langle Ag^2 \rangle = \frac{1}{2}\langle A \otimes A \rangle : \left(u \otimes u - \frac{1}{3}|u|^2 I \right)$$

• Straightforward computations on Gaussian integrals give

$$\begin{aligned} \langle A_{ij}A_{kl} \rangle &= \delta_{ik}\delta_{jl} + \delta_{il}\delta_{jk} - \frac{2}{3}\delta_{ij}\delta_{kl} \\ \langle \hat{A}_{ij}A_{kl} \rangle &= \nu \left(\delta_{ik}\delta_{jl} + \delta_{il}\delta_{jk} - \frac{2}{3}\delta_{ij}\delta_{kl} \right) \end{aligned}$$

so that

$$\frac{1}{\epsilon}\langle Ag_{\epsilon} \rangle \rightarrow \left(u \otimes u - \frac{1}{3}|u|^2 I \right) - \nu D(u)$$

- Substituting this relation in the local conservation of momentum

$$\partial_t \langle v g_\epsilon \rangle + \operatorname{div}_x \frac{1}{\epsilon} \langle A g_\epsilon \rangle + \nabla_x \frac{1}{\epsilon} \langle \frac{1}{3} |v|^2 g_\epsilon \rangle = 0$$

and passing to the limit shows that

$$\partial_t u + \operatorname{div}_x (u \otimes u) - \nu \Delta_x u = 0 \text{ modulo gradients}$$

which is precisely the Navier-Stokes motion equation (since $\operatorname{div}_x u = 0$, one has $\operatorname{div}_x (u \otimes u) = u \cdot \nabla_x u$ and $\operatorname{div}_x D(u) = \Delta_x u$).

- The relation above for $\langle \hat{A}_{ij} A_{kl} \rangle$ shows that

$$\nu = \frac{1}{10} \langle \hat{A} : A \rangle = \frac{1}{10} \langle \hat{A} : \mathcal{L} \hat{A} \rangle > 0$$

since $\mathcal{L} \geq 0$ and $\hat{A} \perp \ker \mathcal{L}$.

Other limits

- From Boltzmann to incompressible Euler: the scaling is

$$\text{St} = \text{Ma} = \epsilon \ll 1, \quad \pi \text{Kn} = \epsilon^a \text{ with } a > 1$$

i.e. one seeks solutions of the scaled Boltzmann equation

$$\epsilon \partial_t F_\epsilon + v \cdot \nabla_x F_\epsilon = \frac{1}{\epsilon^a} \mathcal{B}(F_\epsilon, F_\epsilon)$$

in the form

$$F_\epsilon = \mathcal{M}_{(1,0,1)} + \epsilon f_\epsilon$$

- Formal argument by C. Bardos-F.G.-D. Levermore (J. Stat. Phys. 1991)
- Proof with dissipative solutions of Euler by L. Saint-Raymond (Arch. Rat. Mech. Anal. 2002)

- From Boltzmann to Stokes: the scaling is

$$St = \pi Kn = \epsilon \ll 1, \quad Ma = \epsilon^a \text{ with } a > 1$$

i.e. one seeks solutions of the scaled Boltzmann equation

$$\epsilon \partial_t F_\epsilon + v \cdot \nabla_x F_\epsilon = \frac{1}{\epsilon} \mathcal{B}(F_\epsilon, F_\epsilon)$$

in the form

$$F_\epsilon = \mathcal{M}_{(1,0,1)} + \epsilon^a f_\epsilon$$

- Formal argument by C. Bardos-F.G.-D. Levermore (J. Stat. Phys. 1991)
- Proof by F.G.-D. Levermore (Comm. Pure Appl. Math. 2002)

- From Boltzmann to the acoustic system: the scaling is

$$St = 1, \quad \pi Kn = \epsilon$$

i.e. one seeks solutions of the scaled Boltzmann equation

$$\partial_t F_\epsilon + v \cdot \nabla_x F_\epsilon = \frac{1}{\epsilon} \mathcal{B}(F_\epsilon, F_\epsilon)$$

in the form

$$F_\epsilon = \mathcal{M}_{(1,0,1)} + \epsilon^c f_\epsilon, \quad \text{with } c > 0$$

- Proof by F.G.-D. Levermore (Comm. Pure Appl. Math. 2002) for $c > \frac{1}{2}$