

Nonresonant Velocity Averaging and the Vlasov-Maxwell System

François Golse
Université Paris 7 & Laboratoire J.-L. Lions,
golse@math.jussieu.fr

Mantova, May 15th –17th 2005

Non resonant wave + transport systems

- We consider systems of the form

$$\square_{t,x}u = f, \quad (\partial_t + v(\xi) \cdot \nabla_x)f = D_\xi^m g, \quad x, \xi \in \mathbf{R}^N, \quad t > 0$$

where $g \equiv g(t, x, \xi)$ is a data, while $(u, f) \equiv (u(t, x, \xi), f(t, x, \xi))$ is the unknown.

- We call the above system **nonresonant** iff $|v(\xi)| < 1$ for each $\xi \in \mathbf{R}^N$ — here 1 is the speed of propagation associated to the d'Alembert operator $\square_{t,x} = \partial_{tt} - \Delta_x$.

- The above system is supplemented with the initial conditions

$$u|_{t=0} = u_0, \quad \partial_t u|_{t=0} = u'_0, \quad f|_{t=0} = f_0.$$

An example: the relativistic Vlasov-Maxwell system

- Consider the relativistic Vlasov equation

$$(\partial_t + v(\xi) \cdot \nabla_x) f = -\operatorname{div}_\xi((E + v(\xi) \times B) f), \quad x, \xi \in \mathbf{R}^3, \quad t > 0$$

coupled to the system of Maxwell equations

$$\begin{aligned} \partial_t E + \operatorname{curl}_x B &= -j_f, & \operatorname{div}_x E &= \rho_f, \\ \partial_t B - \operatorname{curl}_x E &= 0, & \operatorname{div}_x B &= 0, \end{aligned}$$

where

$$v(\xi) = \frac{\xi}{\sqrt{1+|\xi|^2}}, \quad \rho_f(t, x) = \int_{\mathbf{R}^3} f d\xi, \quad j_f(t, x) = \int_{\mathbf{R}^3} v(\xi) f d\xi$$

- Equivalently, one can represent the electromagnetic field (E, B) in terms of a distribution of gauge potentials $u \equiv u(t, x, \xi)$ (distribution of Liénard-Wiechert potentials) that satisfies

$$\square_{t,x} u(t, x, \xi) = f(t, x, \xi), \quad x, \xi \in \mathbf{R}^3, \quad t > 0$$

- Then (modulo fixing the initial conditions)

$$E = -\partial_t \int_{\mathbf{R}^3} v(\xi) u d\xi - \nabla_x \int_{\mathbf{R}^3} u d\xi, \quad B = \text{curl}_x \int_{\mathbf{R}^3} v(\xi) u d\xi$$

- The electromagnetic potential satisfies the Lorentz gauge

$$\partial_t \int_{\mathbf{R}^3} u d\xi + \text{div}_x \int_{\mathbf{R}^3} v(\xi) u d\xi = 0,$$

as a consequence of the continuity equation

$$\partial_t \rho_f + \text{div}_x j_f = 0.$$

- Then, the relativistic Vlasov-Maxwell system becomes

$$\square_{t,x} u = f, \quad (\partial_t + v(\xi) \cdot \nabla_x) f = \operatorname{div}_\xi (F[u] f), \quad x, \xi \in \mathbf{R}^3, \quad t > 0$$

$$F[u] = \partial_t \left(A^0 + \int_{\mathbf{R}^3} v(\xi') u d\xi' \right) + \nabla_x \int_{\mathbf{R}^3} u d\xi' \\ - v(\xi) \times \operatorname{curl}_x \left(A^0 + \int_{\mathbf{R}^3} v(\xi') u d\xi' \right)$$

- The initial conditions are

$$u|_{t=0} = \partial_t u|_{t=0} = 0, \quad f|_{t=0} = f^{in},$$

while

$$\square_{t,x} A^0 = 0, \quad A^0|_{t=0} = A_I, \quad \partial_t A^0|_{t=0} = -E^{in}$$

with

$$\operatorname{curl}_x A_I = B^{in}, \quad \operatorname{div}_x A_I = 0$$

- The Vlasov-Maxwell system is nonresonant since

$$|v(\xi)| = \frac{|\xi|}{\sqrt{1+|\xi|^2}} < 1 \text{ for each } \xi \in \mathbf{R}^3$$

(the speed of massive particles is less than the speed of light).

- However, the Vlasov-Maxwell system is not UNIFORMLY nonresonant as $|\xi| \rightarrow +\infty$.

- The only a priori bounds are

$$\begin{aligned} \|f(t)\|_{L^p_{x,\xi}} &= \text{Const.} \\ \iint_{\mathbf{R}^3 \times \mathbf{R}^3} \sqrt{1+|\xi|^2} f(t, x, \xi) dx d\xi \\ + \int_{\mathbf{R}^3} (|E|^2 + |B|^2)(t, x) dx &= \text{Const.} \end{aligned}$$

(in particular, there is no a priori bound on the support of f .)

The Glassey-Strauss theorem (ARMA, 1986)

Theorem. Let $f \in C([0, T) \times \mathbf{R}^3 \times \mathbf{R}^3)$ and $E, B \in C^1([0, T) \times \mathbf{R}^3)$ be a solution of the Vlasov-Maxwell system with $f^{in} \in C_c^1(\mathbf{R}^3 \times \mathbf{R}^3)$ and $E^{in}, B^{in} \in C_c^2(\mathbf{R}^3)$ s.t.

$$\operatorname{div}_x E^{in} = \int_{\mathbf{R}^3} f^{in} d\xi, \quad \operatorname{div}_x B^{in} = 0$$

If

$$\overline{\lim}_{t \rightarrow T^-} \|f(t)\|_{Lip_{x,\xi}} + \|(E, B)(t)\|_{Lip_x} = +\infty$$

then

$$\overline{\lim}_{t \rightarrow T^-} R_f(t) = +\infty$$

where

$$R_f(t) = \inf\{r > 0 \mid f(t, x, \xi) = 0 \text{ for each } x \in \mathbf{R}^3 \text{ and } |\xi| > r\}.$$

•Need to gain 1 derivative on the fields, i.e. 2 derivatives on the gauge potential which is given in terms of momentum-averages of u .

•Assume that

$$\square_{t,x}u = f, \quad (\partial_t + v(\xi) \cdot \nabla_x)f = \operatorname{div}_\xi g \quad \text{with } f, g \in L_{loc}^2(dt dx d\xi)$$

•Classical velocity averaging gives, for each $\phi \in C_c^1(\mathbf{R}^3)$:

$$\int_{\mathbf{R}^3} f(t, x, \xi)\phi(\xi)d\xi \in H_{loc}^{1/4}(\mathbf{R}_t \times \mathbf{R}_x^3)$$

•One gains one more derivative by the energy estimate for the wave equation, so that

$$\int_{\mathbf{R}^3} u(t, x, \xi)\phi(\xi)d\xi \in H_{loc}^{1+1/4}(\mathbf{R}_t \times \mathbf{R}_x^3)$$

One gains $1 + \frac{1}{4}$ derivatives on momentum-averages of u : NOT ENOUGH

Resonant Velocity Averaging

- In fact one can gain 2 derivatives on momentum-averages of u in the nonresonant case — without gaining more on momentum-averages of f .

Theorem. (Bouchut-G-Pallard, *Revista Mat. Iberoam.* 2004) *Let f, g in $L^2_{loc}(\mathbf{R}_t \times \mathbf{R}_x^N \times \mathbf{R}_\xi^N)$ satisfy*

$$\square_{t,x} u = f, \quad (\partial_t + v(\xi) \cdot \nabla_x) f = D_\xi^m g$$

where $v \in C^\infty(\mathbf{R}^N; \mathbf{R}^N)$ is nonresonant, i.e. satisfies $|v(\xi)| < 1$. Then, for each $m \in \mathbf{N}$ and each $\phi \in C_c^\infty(\mathbf{R}_\xi^N)$, one has

$$\int_{\mathbf{R}^3} u(t, x, \xi) \phi(\xi) d\xi \in H^2_{loc}(\mathbf{R} \times \mathbf{R}^N).$$

- This generalizes the fact that $\square_{t,x}$ acts as an elliptic operator on the nullspace of the transport operator whenever $|v(\xi)| < 1$.

- Sketch of proof: Set $T_\xi^\pm = \partial_t \pm v(\xi) \cdot \nabla_x$ and consider the 2nd order differential operator

$$Q_\xi = \square_{t,x} - \lambda T_\xi^- T_\xi^+$$

- First, one checks that

$$\begin{aligned} Q_\xi u &= f - \lambda T_\xi^- \square_{t,x}^{-1} D_\xi^m g = f - \lambda D_\xi^m \square_{t,x}^{-1} T_\xi^- g - \lambda \square_{t,x}^{-1} [T_\xi^-, D_\xi^m] g \\ &= f - \lambda D_\xi^m \square_{t,x}^{-1} T_\xi^- g - \lambda \square_{t,x}^{-1} D_\xi^m v(\xi) \cdot \nabla_x g \\ &= a + d_\xi^m b \in L_{loc}^2(dt dx d\xi) + D_\xi^m L_{loc}^2(dt dx d\xi) \end{aligned}$$

- Then we observe that, for $\xi \in \text{supp } \phi$ and λ such that

$$\sup_{\xi \in \text{supp } \phi} |v(\xi)| < \lambda < 1$$

the operator Q_ξ is elliptic for each $\xi \in \text{supp } \phi$.

- More precisely, denoting by $q_\xi(\omega, k)$ the symbol of Q_ξ , one has

$$\sup_{\xi \in \text{supp } \phi} \left| D_\xi^m \left(\frac{1}{q_\xi(\omega, k)} \right) \right| \leq \frac{C_m}{\omega^2 + |k|^2}$$

where C_m may depend on m but is uniform in ξ .

- Then

$$\int \widehat{u} \phi(\xi) d\xi = \int \frac{\widehat{a}}{q_\xi(\omega, k)} \phi(\xi) d\xi + (-1)^m \int D_\xi^m \left(\frac{\phi(\xi)}{q_\xi(\omega, k)} \right) \widehat{b} d\xi$$

with \widehat{a} and $\widehat{b} \in L^2_{\omega, k, \xi}$ has H^2 -decay in ω, k .

QED

Remarks:

- First, one easily checks that all the assumptions in the Theorem above cannot be dispensed with.
- That one gains 2 derivatives is special to L^2 , because $\square_{t,x}^{-1}$ gains 1 derivative in (t, x) by the energy estimate for the wave equation.

In L^p with $1 < p < \infty$, $\square_{t,x}^{-1}$ gains $1 - (N - 1)|\frac{1}{2} - \frac{1}{p}|$ derivatives in (t, x) (Peral, JFA 1980) whenever $|\frac{1}{2} - \frac{1}{p}| \leq \frac{1}{N-1}$. Using this result and the Mihlin-Hörmander theorem on L^p multipliers, the same proof as above shows that

$$\int_{\mathbf{R}^N} u(t, x, \xi) \phi(\xi) d\xi \in W_{loc}^{1+\gamma, p}(\mathbf{R} \times \mathbf{R}^N) \text{ with } \gamma = 1 - (N - 1)|\frac{1}{2} - \frac{1}{p}|$$

This result suggests a gain of 1 derivative in L^∞ — and in any case does not apply in L^∞ .

A division lemma

- Let Y be the forward fundamental solution of $\square_{t,x}$, i.e.

$$\square_{t,x}Y = \delta_{(0,0)}, \quad \text{supp } Y \subset \mathbf{R}_+ \times \mathbf{R}^N$$

— for instance, in space dimension $N = 3$, one has

$$Y(t, x) = \mathbf{1}_{t \geq 0} \frac{\delta(t - |x|)}{4\pi t}$$

- Recall that the Lorentz boosts

$$L_j = x_j \partial_t + t \partial_{x_j}, \quad j = 1, \dots, N$$

commute with the d'Alembertian

$$[\square_{t,x}, L_j] = 0, \quad \text{so that } L_j Y = 0, \quad j = 1, \dots, N.$$

Lemma. *Let $N \geq 2$. For each $\xi \in \mathbf{R}^N$, there exists $b_{ij}^k \equiv b_{ij}^k(t, x, \xi)$ is C^∞ on $\mathbf{R}^{1+N} \setminus 0$ and homogeneous of degree $-k$ in (t, x) such that*

(i) the homogeneous distribution $b_{ij}^2 Y$ of degree $-1 - N$ on $\mathbf{R}^{1+N} \setminus 0$ has null residue at the origin, and

(ii) there exists an extension of $b_{ij}^2 Y$ as a homogeneous distribution of degree $-1 - N$ on $\mathbf{R}^{1+N} \setminus 0$, still denoted $b_{ij}^2 Y$, that satisfies

$$\partial_{ij} Y = T^2(b_{ij}^0 Y) + T(b_{ij}^1 Y) + b_{ij}^2 Y, \quad i, j = 0, \dots, N.$$

Here T is the advection operator $T = \partial_t + v(\xi) \cdot \nabla_x$.

- The null residue condition reads

$$\int_{\mathbf{S}^2} b_{ij}^2(1, y) d\sigma(y) = 0 \quad \text{if } N = 3,$$

$$\int_{|y| \leq 1} b_{ij}^2(1, y) \frac{dy}{\sqrt{1-|y|^2}} = 0 \quad \text{if } N = 2.$$

- Next we use the above lemma to estimate the derivatives of the fields

$$\partial_{ij} \int m(\xi) u(t, x, \xi) d\xi = \sum_{k=0}^2 \int m(\xi) \left(b_{ij}^{k-l} Y \star T^l(\mathbf{1}_{t \geq 0} f)(t, x, \xi) \right) d\xi$$

Here, m denotes any C^∞ function with compact support that coincides with either 1 or each component of $v(\xi)$ on the ξ -support of f .

The idea is to use the Vlasov equation to compute $T^l(\mathbf{1}_{t \geq 0} f)$ and integrate by parts to bring the ξ -derivatives to bear on b_{ij}^{k-l} and m .

- Worst term is for $l = 0$:

$$\int m(\xi) \left(b_{ij}^2 Y \star (\mathbf{1}_{t \geq 0} f) \right) (t, x, \xi) d\xi.$$

By using the null residue condition, write this term as

$$\begin{aligned} & \int m(\xi) \int_{\epsilon}^t \int_{\mathbf{S}^2} b_{ij}^2(1, \omega, \xi) f(t-s, x-s\omega, \xi) \frac{d\sigma(\omega)}{4\pi s} ds d\xi \\ & + \int m(\xi) \int_0^{\epsilon} \int_{\mathbf{S}^2} b_{ij}^2(1, \omega, \xi) \frac{f(t-s, x-s\omega, \xi) - f(t, x, \omega)}{4\pi s} d\sigma(\omega) ds d\xi \end{aligned}$$

- If the size $R_f(t)$ of the ξ -support of f is bounded on $[0, T)$, i.e. if $\overline{\lim}_{t \rightarrow T^-} R_f(t) < +\infty$, this term is bounded by

$$C(1 + \ln_+(t \|\nabla_x f\|_{L^\infty}))$$

•Hence, the Lipschitz semi-norm $N(t) = \|\nabla_{x,\xi} f(t, \cdot, \cdot)\|_{L^\infty}$ satisfies a logarithmic Gronwall inequality

$$N(t) \leq N(0) + \int_0^t (1 + \ln_+ N(s))N(s)ds, \quad t \in [0, T].$$

Therefore N is uniformly bounded on $[0, T]$, which implies in turn that the fields $(E, B) \in L^\infty(0, T; W^{1,\infty}(\mathbf{R}^3))$.