

# Fluid Dynamics from Kinetic Equations

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LECTURE 6

FROM BOLTZMANN TO INCOMPRESSIBLE NAVIER STOKES

CONVERGENCE PROOF

## The incompressible Navier-Stokes scaling

- Consider the dimensionless Boltzmann equation in the incompressible Navier-Stokes scaling, i.e. with  $\text{St} = \pi \text{Kn} = \epsilon \ll 1$ :

$$\epsilon \partial_t F_\epsilon + v \cdot \nabla_x F_\epsilon = \frac{1}{\epsilon} \mathcal{B}(F_\epsilon, F_\epsilon)$$

- Start with an initial data that is a perturbation of some uniform Maxwellian (say, the centered reduced Gaussian  $M = M_{1,0,1}$ ) with Mach number  $\text{Ma} = O(\epsilon)$ :

$$F_\epsilon^{in} = M_{1,0,1} + \epsilon f_\epsilon^{in}$$

- Example 1: pick  $u^{in} \in L^2(\mathbb{R}^3)$  a divergence-free vector field; then the distribution function

$$F_\epsilon^{in}(x, v) = M_{1, \epsilon u^{in}(x), 1}(v)$$

is of the type above.

- Example 2: If in addition  $\theta^{in} \in L^2 \cap L^\infty(\mathbf{R}^3)$ , the distribution function

$$F_\epsilon^{in}(x, v) = M_{1-\epsilon\theta^{in}(x), \frac{\epsilon u^{in}(x)}{1-\epsilon\theta^{in}(x)}, \frac{1}{1-\epsilon\theta^{in}(x)}}(v)$$

is also of the type above. (Pick  $0 < \epsilon < \frac{1}{\|\theta^{in}\|_{L^\infty}}$ , then  $1 - \epsilon\theta^{in} > 0$  a.e.).

- Problem: to prove that

$$\frac{1}{\epsilon} \int_{\mathbf{R}^3} v F_\epsilon(t, x, v) dv \rightarrow u(t, x) \text{ as } \epsilon \rightarrow 0$$

where  $u$  solves the incompressible Navier-Stokes equations

$$\begin{aligned} \partial_t u + u \cdot \nabla_x u + \nabla_x p &= \nu \Delta_x u, & \operatorname{div}_x u &= 0 \\ u|_{t=0} &= u^{in} \end{aligned}$$

The viscosity  $\nu$  is given by the same formula as in the Chapman-Enskog expansion.

## A priori estimates

- The only a priori estimate satisfied by renormalized solutions to the Boltzmann equation is the DiPerna-Lions entropy inequality:

$$H(F_\epsilon|M)(t) + \frac{1}{\epsilon^2} \int_0^t \int_{\mathbf{R}^3} \iiint_{\mathbf{R}^3 \times \mathbf{R}^3 \times \mathbf{S}^2} d(F_\epsilon) |(v - v_*) \cdot \omega| dv dv_* d\omega dx ds \leq H(F_\epsilon^{in}|M)$$

- Notation:

$$H(f|g) = \iint_{\mathbf{R}^3 \times \mathbf{R}^3} \left( f \ln \left( \frac{f}{g} \right) - f + g \right) dx dv \quad (\text{relative entropy})$$

$$d(f) = \frac{1}{4} (f' f'_* - f f_*) \ln \left( \frac{f' f'_*}{f f_*} \right) \quad (\text{dissipation integrand})$$

- Introduce the **relative number density**, and the **relative number density fluctuation**:

$$G_\epsilon = \frac{F_\epsilon}{M}, \quad g_\epsilon = \frac{F_\epsilon - M}{\epsilon M}$$

- Pointwise inequalities: one easily checks that

$$\begin{aligned} (\sqrt{G_\epsilon} - 1)^2 &\leq C(G_\epsilon \ln G_\epsilon - G_\epsilon + 1) \\ \left( \sqrt{G'_\epsilon G'_{\epsilon*}} - \sqrt{G_\epsilon G_{\epsilon*}} \right)^2 &\leq \frac{1}{4}(G'_\epsilon G'_{\epsilon*} - G_\epsilon G_{\epsilon*}) \ln \left( \frac{G'_\epsilon G'_{\epsilon*}}{G_\epsilon G_{\epsilon*}} \right) \\ &= d(G_\epsilon) \end{aligned}$$

- Notice that  $Z \ln Z - Z + 1 \sim \frac{1}{2}(Z - 1)^2$  near  $Z = 1$ .

- Express that the initial data is a **perturbation** of the uniform Maxwellian  $M$  with Mach number  $\text{Ma} = O(\epsilon)$ :

$$H(F_\epsilon^{in}) \leq C^{in} \epsilon^2$$

- With the DiPerna-Lions entropy inequality, and the pointwise inequalities above, one gets the following **uniform in  $\epsilon$**  bounds

$$\int_0^{+\infty} \int_{\mathbf{R}^3} \iint_{\mathbf{R}^3 \times \mathbf{R}^3 \times \mathbf{S}^2} \left( \sqrt{G'_\epsilon G'_{\epsilon*}} - \sqrt{G_\epsilon G_{\epsilon*}} \right)^2 d\mu dx dt \leq C\epsilon^4$$

$$\iint_{\mathbf{R}^3 \times \mathbf{R}^3} (\sqrt{G_\epsilon} - 1)^2 M dv dx \leq C\epsilon^2$$

where  $\mu$  is the **collision measure**:

$$d\mu(v, v_*, \omega) = |(v - v_*) \cdot \omega| d\omega M_* dv_* M dv$$

## References

- C. Bardos, F. G., D. Levermore: CPAM 1993 (Stokes limit+stationary incompressible Navier-Stokes, assuming local conservation of momentum + nonlinear compactness estimate)
- P.-L. Lions, N. Masmoudi: ARMA 2000 (evolution Navier-Stokes under the same assumptions)
- C.B.-F.G.-D.L.: ARMA 2000 + F.G.-D.L.: CPAM 2002 (local conservation of momentum and energy PROVED in the hydrodynamic limit, for the acoustic and Stokes limits)
- L. Saint-Raymond (CPDEs 2002 + Ann. Sci. ENS 2003): complete derivation of incompressible Navier-Stokes from BGK

- F.G.+L.S.-R.: (Invent. Math. 2004) complete derivation of incompressible Navier-Stokes from Boltzmann for cutoff Maxwell molecules
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- N. M.+L.S.-R. (CPAM 2003) Stokes limit for the boundary value problem

## The BGL Program (CPAM 1993)

- Let  $F_\epsilon^{in} \geq 0$  be any sequence of measurable functions satisfying the entropy bound  $H(F_\epsilon^{in}|M) \leq C^{in}\epsilon^2$ , and let  $F_\epsilon$  be a renormalized solution of the scaled Boltzmann equation

$$\epsilon \partial_t F_\epsilon + v \cdot \nabla_x F_\epsilon = \frac{1}{\epsilon} \mathcal{B}(F_\epsilon, F_\epsilon), \quad F_\epsilon|_{t=0} = F_\epsilon^{in}$$

- Let  $g_\epsilon \equiv g_\epsilon(x, v)$  be such that  $G_\epsilon := 1 + \epsilon g_\epsilon \geq 0$  a.e.. We say that  $g_\epsilon \rightarrow g$  **entropically at rate  $\epsilon$**  as  $\epsilon \rightarrow 0$  iff

$$g_\epsilon \rightarrow g \text{ in } w - L_{loc}^1(M dv dx), \text{ and } \frac{1}{\epsilon^2} H(M G_\epsilon | M) \rightarrow \frac{1}{2} \iint g^2 M dv dx$$

**Theorem.** *Assume that*

$$\frac{F_\epsilon^{in}(x, v) - M(v)}{\epsilon M(v)} \rightarrow u^{in}(x) \cdot v$$

*entropically at rate  $\epsilon$ . Then the family of bulk velocity fluctuations*

$$\frac{1}{\epsilon} \int_{\mathbf{R}^3} v F_\epsilon dv$$

*is relatively compact in  $w - L_{loc}^1(dt dx)$  and each of its limit points as  $\epsilon \rightarrow 0$  is a Leray solution of*

$$\partial_t u + \operatorname{div}_x(u \otimes u) + \nabla_x p = \nu \Delta_x u, \quad \operatorname{div}_x u = 0, \quad u|_{t=0} = u^{in}$$

*with viscosity given by the formula*

$$\nu = \frac{1}{10} \int A : \hat{A} M dv$$

*where  $\hat{A} = \mathcal{L}^{-1} A$*

## Method of proof

- Renormalization: pick  $\gamma \in C^\infty(\mathbf{R}_+)$  a nonincreasing function such that

$$\gamma|_{[0,3/2]} \equiv 1, \quad \gamma|_{[2,+\infty)} \equiv 0; \quad \text{set } \hat{\gamma}(z) = \frac{d}{dz}((z-1)\gamma(z))$$

- The Boltzmann equation is renormalized (relatively to  $M$ ) as follows:

$$\partial_t(g_\epsilon \gamma_\epsilon) + \frac{1}{\epsilon} v \cdot \nabla_x(g_\epsilon \gamma_\epsilon) = \frac{1}{\epsilon^3} \hat{\gamma}_\epsilon Q(G_\epsilon, G_\epsilon)$$

where  $\gamma_\epsilon := \gamma(G_\epsilon)$ ,  $\hat{\gamma}_\epsilon = \hat{\gamma}(G_\epsilon)$  and  $Q(G, G) = M^{-1} \mathcal{B}(MG, MG)$

- **Continuity equation** Renormalized solutions of the Boltzmann equation satisfy the **local conservation of mass**:

$$\epsilon \partial_t \langle g_\epsilon \rangle + \operatorname{div}_x \langle v g_\epsilon \rangle = 0$$

- The entropy bound implies that

$$(1 + |v|^2) g_\epsilon \text{ is relatively compact in } w - L^1_{loc}(dtdx; L^1(Mdv))$$

Modulo extraction of a subsequence

$$g_\epsilon \rightarrow g \text{ in } w - L^1_{loc}(dtdx; L^1(Mdv))$$

and hence  $\langle v g_\epsilon \rangle \rightarrow \langle v g \rangle =: u$  in  $w - L^1_{loc}(dtdx)$ ; passing to the limit in the continuity equation leads to **the incompressibility condition**

$$\operatorname{div}_x u = 0$$

• High velocity truncation: pick  $K > 6$  and set  $K_\epsilon = K |\ln \epsilon|$ ; for each function  $\xi \equiv \xi(v)$ , define  $\xi_{K_\epsilon}(v) = \xi(v) \mathbf{1}_{|v|^2 \leq K_\epsilon}$

• Multiply both sides of the scaled, renormalized Boltzmann equation by each component of  $v_{K_\epsilon}$ :

$$\partial_t \langle v_{K_\epsilon} g_\epsilon \gamma_\epsilon \rangle + \operatorname{div}_x \mathbf{F}_\epsilon(A) + \nabla_x \frac{1}{\epsilon} \langle \frac{1}{3} |v|_{K_\epsilon}^2 g_\epsilon \gamma_\epsilon \rangle = \mathbf{D}_\epsilon(v)$$

where

$$\mathbf{F}_\epsilon(A) = \frac{1}{\epsilon} \langle A_{K_\epsilon} g_\epsilon \gamma_\epsilon \rangle, \quad \mathbf{D}_\epsilon(v) = \frac{1}{\epsilon^3} \langle\langle v_{K_\epsilon} \hat{\gamma}_\epsilon (G'_\epsilon G'_{\epsilon*} - G_\epsilon G_{\epsilon*}) \rangle\rangle$$

• Notation: with  $d\mu = |(v - v_*) \cdot \omega| M dv M_* dv_* d\omega$  (collision measure)

$$\langle \phi \rangle = \int_{\mathbf{R}^3} \phi(v) M dv, \quad \langle\langle \psi \rangle\rangle = \iiint_{\mathbf{R}^3 \times \mathbf{R}^3 \times \mathbf{S}^2} \psi(v, v_*, \omega) d\mu$$

- The plan is to prove that, modulo extraction of a subsequence

$$\begin{array}{ll}
 \langle v_{K_\epsilon} g_\epsilon \gamma_\epsilon \rangle \rightarrow \langle v g \rangle =: u & \text{in } w - L_{loc}^1(\mathbf{R}_+ \times \mathbf{R}^3) \\
 \mathbf{D}_\epsilon(v) \rightarrow 0 & \text{in } L_{loc}^1(\mathbf{R}_+ \times \mathbf{R}^3) \text{ and} \\
 P(\operatorname{div}_x \mathbf{F}_\epsilon(A)) \rightarrow P \operatorname{div}_x(u^{\otimes 2}) - \nu \Delta_x u & \text{in } w - L_{loc}^1(dt, W_{x,loc}^{-s,1})
 \end{array}$$

for  $s > 1$  as  $\epsilon \rightarrow 0$ , where  $P$  is the Leray projection.

## Conservation defects $\rightarrow 0$

(as in FG+DL, CPAM 2002, but simpler)

**Proposition.**  $D_\epsilon(v) \rightarrow 0$  in  $L^1_{loc}(\mathbb{R}_+ \times \mathbb{R}^3)$  as  $\epsilon \rightarrow 0$ .

• Split the conservation defect as

$$\mathbf{D}_\epsilon^1(v) = \frac{1}{\epsilon^3} \left\langle\left\langle v_{K_\epsilon} \hat{\gamma}_\epsilon \left( \sqrt{G'_\epsilon G'_{\epsilon^*}} - \sqrt{G_\epsilon G_\epsilon} \right)^2 \right\rangle\right\rangle$$

$$\mathbf{D}_\epsilon^2(v) = \frac{1}{\epsilon^3} \left\langle\left\langle v_{K_\epsilon} \hat{\gamma}_\epsilon \left( \sqrt{G'_\epsilon G'_{\epsilon^*}} - \sqrt{G_\epsilon G_\epsilon} \right) \sqrt{G_\epsilon G_\epsilon} \right\rangle\right\rangle$$

That  $\mathbf{D}_\epsilon^1(v) \rightarrow 0$  comes from the entropy production estimate.

•Setting  $\Xi_\epsilon = \frac{1}{\epsilon^2} \left( \sqrt{G'_\epsilon G'_{\epsilon*}} - \sqrt{G_\epsilon G_\epsilon} \right) \sqrt{G_\epsilon G_\epsilon}$ , we further split  $\mathbf{D}_\epsilon^2(v)$  into

$$\begin{aligned} \mathbf{D}_\epsilon^2(v) = & -\frac{2}{\epsilon} \left\langle\left\langle v \mathbf{1}_{|v|^2 > K_\epsilon} \hat{\gamma}_\epsilon \Xi_\epsilon \right\rangle\right\rangle + \frac{2}{\epsilon} \left\langle\left\langle v \hat{\gamma}_\epsilon (1 - \hat{\gamma}_{\epsilon*} \hat{\gamma}'_\epsilon \hat{\gamma}_{\epsilon*}) \Xi_\epsilon \right\rangle\right\rangle \\ & + \frac{1}{\epsilon} \left\langle\left\langle (v + v_1) \hat{\gamma}_\epsilon \hat{\gamma}_{\epsilon*} \hat{\gamma}'_\epsilon \hat{\gamma}_{\epsilon*} \Xi_\epsilon \right\rangle\right\rangle \end{aligned}$$

The first and third terms are easily mastered by the entropy production bound and classical estimates on the tail of Gaussian distributions.

•Sending the second term to 0 requires knowing that

$$(1 + |v|) \left( \frac{\sqrt{G_\epsilon} - 1}{\epsilon} \right)^2 \text{ is uniformly integrable on } [0, T] \times K \times \mathbf{R}^3$$

for the measure  $dt dx M dv$ , for each  $T > 0$  and each compact  $K \subset \mathbf{R}^3$ .

## Asymptotic behavior of the momentum flux

**Proposition.** Denoting by  $\Pi$  the  $L^2(Mdv)$ -orthogonal projection on  $\ker \mathcal{L}$

$$\mathbf{F}_\epsilon(A) = 2 \left\langle A \left( \Pi \frac{\sqrt{G_\epsilon} - 1}{\epsilon} \right)^2 \right\rangle - 2 \left\langle \hat{A} \frac{1}{\epsilon^2} \mathcal{Q}(\sqrt{G_\epsilon}, \sqrt{G_\epsilon}) \right\rangle + o(1)_{L^1_{loc}(dtdx)}$$

The proof is based upon splitting  $\mathbf{F}_\epsilon(A)$  as

$$\mathbf{F}_\epsilon(A) = \left\langle A_{K_\epsilon} \gamma_\epsilon \left( \frac{\sqrt{G_\epsilon} - 1}{\epsilon} \right)^2 \right\rangle + \frac{2}{\epsilon} \left\langle A_{K_\epsilon} \gamma_\epsilon \frac{\sqrt{G_\epsilon} - 1}{\epsilon} \right\rangle$$

using the uniform integrability of  $(1 + |v|) \left( \frac{\sqrt{G_\epsilon} - 1}{\epsilon} \right)^2$  and the following consequence thereof

$$\lim_{\epsilon \rightarrow 0} \left\| \frac{\sqrt{G_\epsilon} - 1}{\epsilon} - \Pi \frac{\sqrt{G_\epsilon} - 1}{\epsilon} \right\|_{L^2_{loc}(dtdx; L^2((1+|v|)Mdv))} = 0$$

- By the entropy production estimate, modulo extraction of a subsequence

$$\frac{1}{\epsilon^2} \left( \sqrt{G'_\epsilon G'_{\epsilon^*}} - \sqrt{G_\epsilon G_\epsilon} \right) \rightarrow q$$

and passing to the limit in the scaled, renormalized Boltzmann equation leads to

$$\iint_{\mathbf{R}^3 \times \mathbf{S}^2} q |(v - v_*) \cdot \omega| M_* dv_* d\omega = v \cdot \nabla_x g = \frac{1}{2} A : \nabla_x u + \text{odd in } v$$

- Since  $\frac{\sqrt{G_\epsilon} - 1}{\epsilon} \simeq \frac{1}{2} g_\epsilon \gamma_\epsilon$ , one gets

$$\mathbf{F}_\epsilon(A) = A(\langle v_{K_\epsilon} g_\epsilon \gamma_\epsilon \rangle) - \nu(\nabla_x u + (\nabla_x u)^T) + o(1)_{w-L^1_{loc}(dt dx)}$$

(remember that  $A(u) = u \otimes u - \frac{1}{3}|u|^2 I$ ), while

$$\langle v_{K_\epsilon} g_\epsilon \gamma_\epsilon \rangle \rightarrow u \text{ in } w - L^1_{loc}(\mathbf{R}_+ \times \mathbf{R}^3)$$

## Strong compactness

- In order to pass to the limit in the quadratic term  $A(\langle v_{K_\epsilon} g_\epsilon \gamma_\epsilon \rangle)$ , one needs **strong- $L^2$  compactness of  $\langle v_{K_\epsilon} g_\epsilon \gamma_\epsilon \rangle$** .
- Velocity averaging provides strong compactness **in the  $x$ -variable**:

$$\left( \frac{\sqrt{\epsilon^\alpha + G_\epsilon} - 1}{\epsilon} \right)^2 \text{ is locally uniformly integrable on } \mathbf{R}_+ \times \mathbf{R}^3 \times \mathbf{R}^3$$
$$(\epsilon \partial_t + v \cdot \nabla_x) \frac{\sqrt{\epsilon^\alpha + G_\epsilon} - 1}{\epsilon} \text{ is bounded in } L^1_{loc}(\mathbf{R}_+ \times \mathbf{R}^3 \times \mathbf{R}^3)$$

This implies that, for each  $T > 0$  and each compact  $K \subset \mathbf{R}^3$ ,

$$\int_0^T \int_K |\langle v_{K_\epsilon} g_\epsilon \gamma_\epsilon \rangle(t, x + y) - \langle v_{K_\epsilon} g_\epsilon \gamma_\epsilon \rangle(t, x)|^2 dx dt \rightarrow 0$$

as  $|y| \rightarrow 0$ , uniformly in  $\epsilon > 0$

- It remains to get compactness in the time variable. Observe that

$\partial_t P \langle v_{K_\epsilon} g_\epsilon \gamma_\epsilon \rangle = P(\mathbf{D}_\epsilon(v) - \operatorname{div}_x \mathbf{F}_\epsilon(A))$  is bounded in  $L^1_{loc}(dt, W^{-s,1}_{x,loc})$   
 (Recall that  $\mathbf{D}_\epsilon(v) \rightarrow 0$  while  $\mathbf{F}_\epsilon(A)$  is bounded in  $L^1_{loc}(dtdx)$ ).

- Together with the compactness in the  $x$ -variable that follows from velocity averaging, this implies that

$$P \langle v_{K_\epsilon} g_\epsilon \gamma_\epsilon \rangle \rightarrow u \text{ in } L^2_{loc}(dtdx)$$

- Recall that  $\langle v_{K_\epsilon} g_\epsilon \gamma_\epsilon \rangle \rightarrow u$  in  $w - L^2_{loc}(dtdx)$ ; we do not seek to prove that

$$\langle v_{K_\epsilon} g_\epsilon \gamma_\epsilon \rangle \rightarrow u \text{ strongly in } L^2_{loc}(dtdx)$$

## Filtering acoustic waves (PLL+NM, ARMA 2002)

- Instead, we prove that

$$P \operatorname{div}_x \left( \langle v_{K_\epsilon} g_\epsilon \gamma_\epsilon \rangle^{\otimes 2} \right) \rightarrow P \operatorname{div}_x \left( u^{\otimes 2} \right) \text{ in } \mathcal{D}'(\mathbf{R}_+^* \times \mathbf{R}^3) \text{ as } \epsilon \rightarrow 0$$

- Observe that

$$\begin{aligned} \epsilon \partial_t \langle v_{K_\epsilon} g_\epsilon \gamma_\epsilon \rangle + \nabla_x \langle \frac{1}{3} |v|_{K_\epsilon}^2 g_\epsilon \gamma_\epsilon \rangle &\rightarrow 0 \text{ in } L_{loc}^1(\mathbf{R}_+; W_{loc}^{-1,1}(\mathbf{R}^3)) \\ \epsilon \partial_t \langle \frac{1}{3} |v|_{K_\epsilon}^2 g_\epsilon \gamma_\epsilon \rangle + \operatorname{div}_x \langle \frac{5}{3} v_{K_\epsilon} g_\epsilon \gamma_\epsilon \rangle &\rightarrow 0 \text{ in } L_{loc}^1(\mathbf{R}_+; W_{loc}^{-1,1}(\mathbf{R}^3)) \end{aligned}$$

as  $\epsilon \rightarrow 0$ .

- Setting  $\nabla_x \pi_\epsilon = (I - P) \langle v_{K_\epsilon} g_\epsilon \gamma_\epsilon \rangle$ , the system above becomes

$$\begin{aligned} \epsilon \partial_t \nabla_x \pi_\epsilon + \nabla_x \langle \frac{1}{3} |v|_{K_\epsilon}^2 g_\epsilon \gamma_\epsilon \rangle &\rightarrow 0 \text{ in } L_{loc}^1(\mathbf{R}_+; W_{loc}^{-1,1}(\mathbf{R}^3)) \\ \epsilon \partial_t \langle \frac{1}{3} |v|_{K_\epsilon}^2 g_\epsilon \gamma_\epsilon \rangle + \frac{5}{3} \Delta_x \pi_\epsilon &\rightarrow 0 \text{ in } L_{loc}^1(\mathbf{R}_+; W_{loc}^{-1,1}(\mathbf{R}^3)) \end{aligned}$$

• Straightforward computation shows that

$$\operatorname{div}_x \left( (\nabla_x \pi_\epsilon)^{\otimes 2} \right) = \frac{1}{2} \nabla_x \left( |\nabla_x \pi_\epsilon|^2 - \frac{3}{5} \langle \frac{1}{3} |v|_{K_\epsilon}^2 g_\epsilon \gamma_\epsilon \rangle^2 \right) + o(1)_{L^1_{loc}(dtdx)}$$

• On the other hand, because the limiting velocity field is divergence-free, one has

$$\nabla_x \pi_\epsilon \rightarrow 0 \text{ in } w - L^2_{loc}(dtdx) \text{ as } \epsilon \rightarrow 0$$

• Splitting

$$\begin{aligned} P \operatorname{div}_x \left( \langle v_{K_\epsilon} g_\epsilon \gamma_\epsilon \rangle^{\otimes 2} \right) &= P \operatorname{div}_x \left( (P \langle v_{K_\epsilon} g_\epsilon \gamma_\epsilon \rangle)^{\otimes 2} \right) + P \operatorname{div}_x \left( (\nabla_x \pi_\epsilon)^{\otimes 2} \right) \\ &\quad + 2P \operatorname{div}_x \left( P \langle v_{K_\epsilon} g_\epsilon \gamma_\epsilon \rangle \vee \nabla_x \pi_\epsilon \right) \end{aligned}$$

The last two terms vanish with  $\epsilon$  while the first converges to  $P \operatorname{div}_x (u^{\otimes 2})$  since  $P \langle v_{K_\epsilon} g_\epsilon \gamma_\epsilon \rangle \rightarrow u$  **strongly** in  $L^2_{loc}(dtdx)$ .

**The key estimates** (as in FG+LSR, Invent. Math. 2004)

**Proposition.** For each  $T > 0$  and each compact  $K \subset \mathbf{R}^3$ , the family  $\left(\frac{\sqrt{G_\epsilon}-1}{\epsilon}\right)^2 (1 + |v|)$  is uniformly integrable on  $[0, T] \times K \times \mathbf{R}^3$  for the measure  $dt dx M dv$ .

**Idea no. 1** We first prove that  $\left(\frac{\sqrt{G_\epsilon}-1}{\epsilon}\right)^2 (1 + |v|)$  is uniformly integrable on  $[0, T] \times K \times \mathbf{R}^3$  for the measure  $dt dx M dv$  **in the  $v$ -variable** .

• We say that  $\phi_\epsilon \equiv \phi_\epsilon(x, y) \in L^1_{x,y}(d\mu(x)d\nu(y))$  is uniformly integrable **in the  $y$ -variable** for the measure  $d\mu(x)d\nu(y)$  iff

$$\int \sup_{\nu(A) < \alpha} \int_A |\phi_\epsilon(x, y)| d\nu(y) d\mu(x) \rightarrow 0 \text{ as } \alpha \rightarrow 0 \text{ uniformly in } \epsilon$$

- Start from the formula

$$\mathcal{L} \left( \frac{\sqrt{G_\epsilon} - 1}{\epsilon} \right) = \epsilon \mathcal{Q} \left( \frac{\sqrt{G_\epsilon} - 1}{\epsilon}, \frac{\sqrt{G_\epsilon} - 1}{\epsilon} \right) - \frac{1}{\epsilon} \mathcal{Q} \left( \sqrt{G_\epsilon}, \sqrt{G_\epsilon} \right)$$

and use the following estimate (G.-Perthame-Sulem, ARMA 1988)

$$\| \mathcal{Q}(f, f) \|_{L^2((1+|v|)^{-1} M dv)} \leq C \|f\|_{L^2(M dv)} \|f\|_{L^2((1+|v|) M dv)}$$

to arrive at

$$\begin{aligned} \left( 1 - O(\epsilon) \left\| \frac{\sqrt{G_\epsilon} - 1}{\epsilon} \right\|_{L^2(M dv)} \right) & \left\| \frac{\sqrt{G_\epsilon} - 1}{\epsilon} - \Pi \frac{\sqrt{G_\epsilon} - 1}{\epsilon} \right\|_{L^2((1+|v|) M dv)} \\ & \leq O(\epsilon)_{L^2_{t,x}} + O(\epsilon) \left\| \frac{\sqrt{G_\epsilon} - 1}{\epsilon} \right\|_{L^2(M dv)}^2 \end{aligned}$$

- This estimates tells us that  $\frac{\sqrt{G_\epsilon} - 1}{\epsilon}$  stays close to its associated infinitesimal Maxwellian  $\Rightarrow$  regularity+decay in  $v$ .

Idea no. 2 Use a  $L^1$ -variant of velocity averaging (FG+LSR, CRAS 2002).

**Lemma.** *Let  $f_n \equiv f_n(x, v)$  be a bounded sequence in  $L^1_{loc}(dx dv)$  such that  $v \cdot \nabla_x f_n$  is also bounded in  $L^1_{loc}(dx dv)$ . Assume that  $f_n$  is locally uniformly integrable in  $v$ . Then*

- $f_n$  is locally uniformly integrable (in  $x, v$ )
- for each test function  $\phi \in L^\infty_{comp}(\mathbf{R}_v^D)$ , the sequence of averages

$$\rho_n^\phi(x) = \int f_n(x, v) \phi(v) dv$$

*is relatively compact in  $L^1_{loc}(dx)$ .*

•Let's prove that the sequence of averages  $\rho_n^\phi$  is locally uniformly integrable (LSR, CPDEs 2002). WLOG, assume that  $f_n$  and  $\phi \geq 0$ .

•Let  $\chi \equiv \chi(t, x, v)$  be the solution to

$$\partial_t \chi + v \cdot \nabla_x \chi = 0, \quad \chi(0, x, v) = \mathbf{1}_A(x)$$

Clearly,  $\chi(t, x, v) = \mathbf{1}_{A_x(t)}(v)$  ( $\chi$  takes the values 0 and 1 only). On the other hand,

$$|A_x(t)| = \int \chi(t, x, v) dv = \int \mathbf{1}_A(x - tv) dv = \frac{|A|}{t^D}$$

•Remark: this is the basic dispersion estimate for the free transport equation.

•Set  $g_n(x, v) = f_n(x, v)\phi(v)$ , and  $v \cdot \nabla_x g_n(x, v) = \phi(v)(v \cdot \nabla_x f_n(x, v))$  :  
 $h_n(x, v) =: g_n$  and  $h_n$  are bounded in  $L^1_{x,v}$  and  $g_n$  is uniformly integrable  
in  $v$ .

•Observe that (hint: integrate by parts the 2nd integral in the r.h.s.)

$$\int_A \int g_n dv dx = \int \int_{A_x(t)} g_n dv dx - \int_0^t \iint h_n(x, v) \chi(s, x, v) dx dv ds$$

The second integral on the r.h.s. is  $O(t) \sup \|h_n\|_{L^1_{x,v}} < \epsilon$  by choosing  $t > 0$  small enough. For that value of  $t$ ,  $|A_x(t)| \rightarrow 0$  as  $|A| \rightarrow 0$ , hence the first integral on the r.h.s. vanishes by uniform integrability in  $v$ .