

Hydrodynamic Limits

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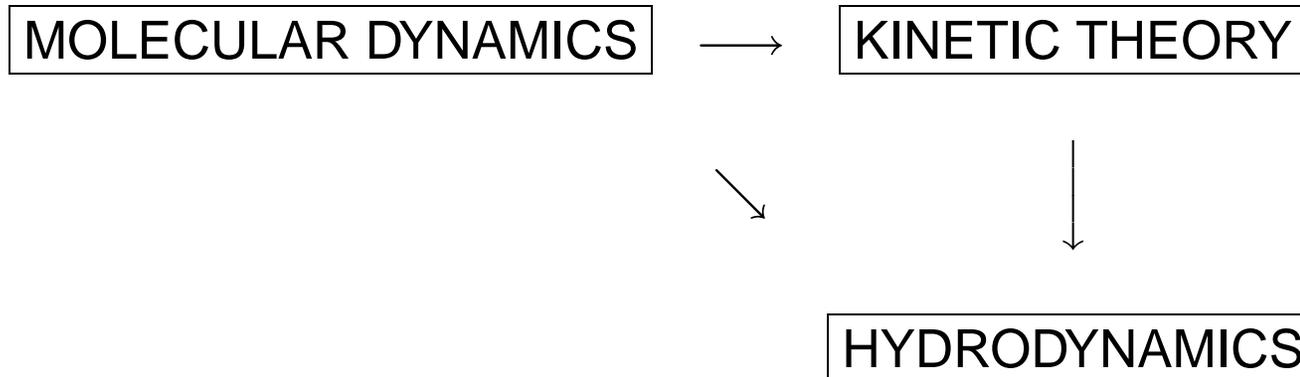
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- In his 1866 paper on the kinetic theory of gases, Maxwell explained how the **viscosity** of a monatomic gas can be computed in terms of data **at the molecular scale** (scattering cross-section and diameter of the molecules) as well as **macroscopic data** (the pressure and temperature in the gas).

- **Hilbert's 6th problem (1900):** "[. . .] Boltzmann's work on the principles of mechanics suggests the problem of developing mathematically the limiting processes [. . .] which lead from the atomistic view to the laws of motion of *continua*"



- Derivation of the [Boltzmann equation](#) from [molecular dynamics](#) on short time intervals by O.E. Lanford (1975)
- “[Formal](#)” derivations of [hydrodynamics](#) from [molecular dynamics](#) by C.B. Morrey (1951)
- [Rigorous](#) results for [stochastic models](#) of molecular dynamics on short time intervals by S. Olla, S.R.S. Varadhan and H.T. Yau (1993)

In this talk, we discuss the derivation of [the Navier-Stokes equations for incompressible flows](#) from [the Boltzmann equation](#)

- Formal argument due to C. Bardos-F.G.-D. Levermore (CRAS 1988, and J. Stat. Phys. 1991)
- Case of global (in time) solutions of Navier-Stokes for small initial data done by C. Bardos-S. Ukai (Math. Models Methods Appl. Sci. 1991)
- Derivation based on a truncated Hilbert expansion sketched by A. DeMasi-R. Esposito-J. Lebowitz (Comm. Pure Appl. Math 1990)

- Case of **initial data of arbitrary size**: loss of regularity in finite time? for solutions to either the Boltzmann or the 3D Navier-Stokes equations \Rightarrow work with **weak solutions**

- Program (**moment method** as in the formal argument + **compactness estimates**) by C. Bardos-F.G.-D. Levermore (Comm. Pure Appl. Math. 1993)

- Various intermediate results in this program obtained by

P.-L. Lions-N. Masmoudi (Arch. Rational Mech. Anal. 2000)

F.G.-D. Levermore (Comm. Pure Appl. Math. 2002)

L. Saint-Raymond (Comm. PDEs 2002, Ann. Scient. ENS 2003)

The Navier-Stokes equations for incompressible flows

• Unknown: the **velocity field** $u \equiv u(t, x) \in \mathbf{R}^3$

• In the absence of external forces (electromagnetic force, gravity...) the velocity field u satisfies

$$\operatorname{div}_x u = 0$$

$$\partial_t u + (u \cdot \nabla_x)u + \nabla_x p = \nu \Delta_x u$$

where $\nu > 0$ is the **kinematic viscosity**

• NOTATION: $((u \cdot \nabla_x)u)^i := \sum_{j=1}^3 u^j \frac{\partial u^i}{\partial x^j}$

• If u is a C^1 divergence-free vector field on \mathbb{R}^3 , then

$$((u \cdot \nabla_x)u)^i = \sum_{j=1}^3 u^j \frac{\partial u^i}{\partial x^j} = \sum_{j=1}^3 \frac{\partial (u^i u^j)}{\partial x^j} =: (\operatorname{div}_x (u \otimes u))^i$$

Theorem. (Leray, Acta. Math. 1934) For each $u^{in} \in L^2(\mathbb{R}^3; \mathbb{R}^3)$ such that $\operatorname{div}_x u^{in} = 0$, there exists $u \in C(\mathbb{R}_+; L^2(\mathbb{R}^3; \mathbb{R}^3))$ that solves the Cauchy problem

$$\begin{aligned} \partial_t u + \operatorname{div}_x (u \otimes u) + \nabla_x p &= \nu \Delta_x u, & \operatorname{div}_x u &= 0 \\ u|_{t=0} &= u^{in} \end{aligned}$$

in the sense of distributions on $\mathbb{R}_+^* \times \mathbb{R}^3$, and satisfies, for each $t > 0$, the energy inequality

$$\frac{1}{2} \int_{\mathbb{R}^3} |u(t, x)|^2 dx + \nu \int_0^t \int_{\mathbb{R}^3} |\nabla_x u(s, x)|^2 dx ds \leq \frac{1}{2} \int_{\mathbb{R}^3} |u^{in}(x)|^2 dx$$

The Boltzmann equation for a hard sphere gas

- Unknown: the **number density** $F \equiv F(t, x, v) \geq 0$ in the 1-particle phase space
- In the absence of external forces (electromagnetic force, gravity...) the number density F satisfies

$$\partial_t F + v \cdot \nabla_x F = \mathcal{C}(F)$$

where $\mathcal{C}(F)$ is **the Boltzmann collision integral**

- Collisions other than **binary** are neglected; besides, these collisions are viewed as **instantaneous** and purely **local** (molecular radius $\simeq 0$)

\mathcal{C} is a bilinear operator acting only on the v variable in F

The Boltzmann collision integral

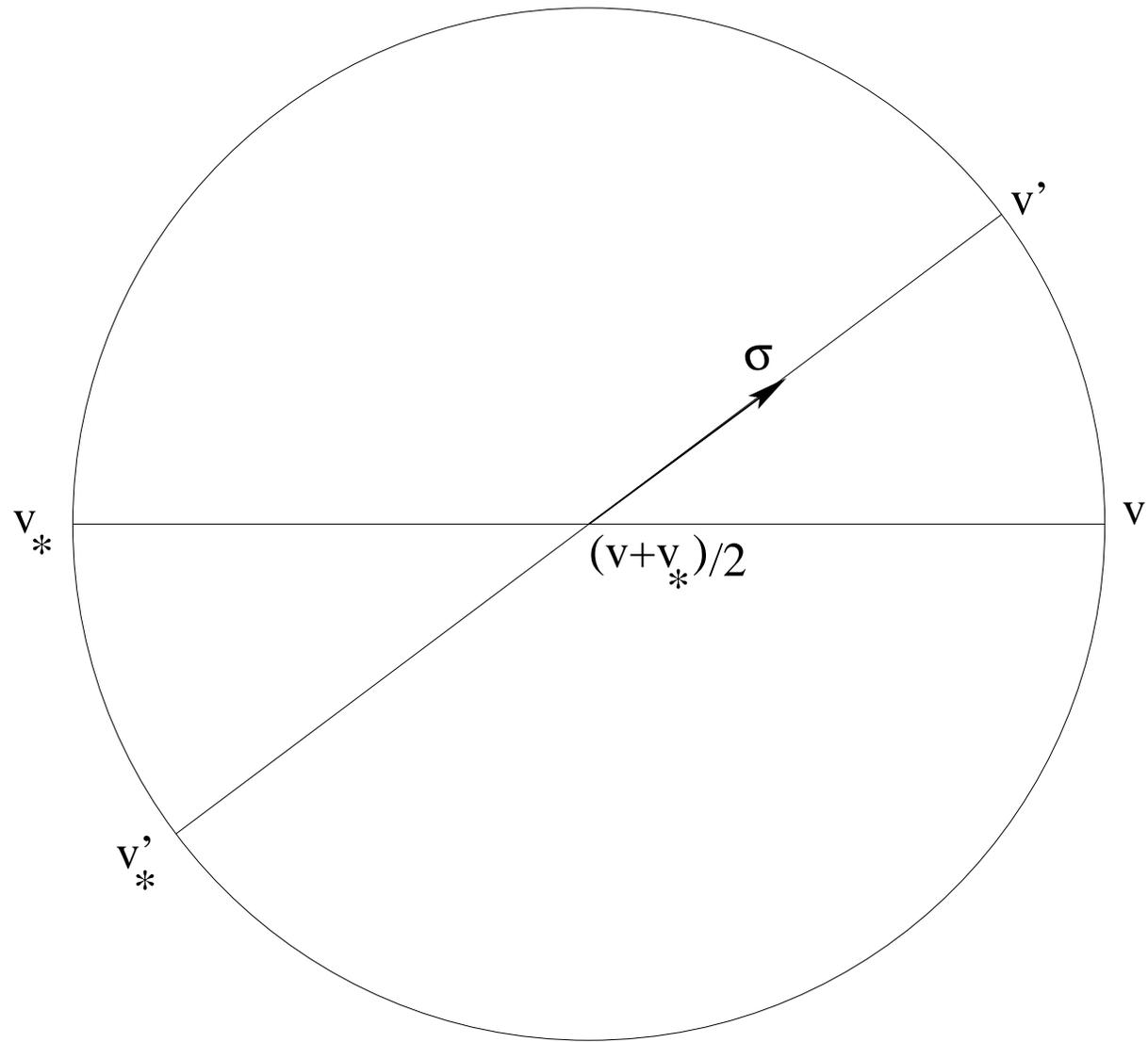
- For a hard sphere gas, the collision integral is

$$\mathcal{C}(F)(v) = \iint_{\mathbf{R}^3 \times \mathbf{S}^2} (F(v')F(v'_*) - F(v)F(v_*)) |v - v_*| dv_* d\sigma$$

where the velocities v' and v'_* are defined in terms of $v, v_* \in \mathbf{R}^3$ and $\sigma \in \mathbf{S}^2$ by

$$\begin{aligned} v' &\equiv v'(v, v_*, \sigma) = \frac{1}{2}(v + v_*) + \frac{1}{2}|v - v_*|\sigma \\ v'_* &\equiv v'_*(v, v_*, \sigma) = \frac{1}{2}(v + v_*) - \frac{1}{2}|v - v_*|\sigma \end{aligned}$$

- Usual notation: F_* , F' and F'_* designate resp. $F(v_*)$, $F(v')$ and $F(v'_*)$



Boltzmann's H Theorem

- Assume that $F \equiv F(v) > 0$ a.e. is rapidly decaying and such that $\ln F$ has polynomial growth at infinity. Then, the local entropy production rate

$$R(F) = - \int_{\mathbf{R}^3} C(F) \ln F dv \geq 0$$

- The following conditions are equivalent:

$$R(F) = 0 \text{ a.e.} \Leftrightarrow C(F) = 0 \text{ a.e.} \Leftrightarrow F \text{ is a Maxwellian}$$

i.e. there exists $\rho, \theta > 0$ and $u \in \mathbf{R}^3$ such that

$$F(v) = \mathcal{M}_{\rho, u, \theta}(v) := \frac{\rho}{(2\pi\theta)^{3/2}} e^{-\frac{|v-u|^2}{2\theta}} \quad \text{a.e. in } v \in \mathbf{R}^3$$

Hydrodynamic limits of kinetic theory leading to **incompressible flows** consider solutions to the Boltzmann equation that are **fluctuations** of some **uniform Maxwellian state**.

•WLOG, we henceforth set this uniform equilibrium state to be

$$M = \mathcal{M}_{(1,0,1)} \quad (\text{the centered, reduced Gaussian distribution})$$

•The size of the number density fluctuations around the equilibrium state M will be measured in terms of the **relative entropy** defined as

$$H(F|M) = \iint_{\mathbf{R}^3 \times \mathbf{R}^3} \left[F \ln \left(\frac{F}{M} \right) - F + M \right] dx dv \quad (\geq 0)$$

for each $F \in L^1(\mathbf{R}^3 \times \mathbf{R}^3)$

Renormalized solutions of $(\partial_t + v \cdot \nabla_x)F = \mathcal{C}(F)$

Theorem. (DiPerna-Lions, Ann. Math. 1990) *For each $F^{in} \geq 0$ a.e. such that $H(F^{in}|M) < +\infty$, there exists $F \in C(\mathbb{R}_+; L^1_{loc}(\mathbb{R}^3 \times \mathbb{R}^3))$ that solves the Cauchy problem*

$$(\partial_t + v \cdot \nabla_x) \ln(1 + F) = \frac{\mathcal{C}(F)}{1 + F}, \quad F|_{t=0} = F^{in}$$

in the sense of distributions on $\mathbb{R}_+^ \times \mathbb{R}^3 \times \mathbb{R}^3$, and satisfies, for each $t > 0$ the entropy inequality*

$$H(F(t)|M) + \int_0^t \int_{\mathbb{R}^3} R(F)(s, x) dx ds \leq H(F^{in}|M).$$

The Navier-Stokes limit theorem

Theorem. Let u^{in} be a divergence-free vector field in $L^2(\mathbb{R}^3; \mathbb{R}^3)$. For each $\epsilon > 0$, let $F_\epsilon \equiv F_\epsilon(t, x, v)$ be a renormalized solution to the Boltzmann equation with initial data

$$F_\epsilon(0, x, v) = \mathcal{M}_{(1, \epsilon u^{in}(\epsilon x), 1)}(v)$$

Then the family of vector fields $u_\epsilon \equiv u_\epsilon(t, x) \in \mathbb{R}^3$ defined by

$$u_\epsilon(t, x) = \frac{1}{\epsilon} \int_{\mathbb{R}^3} v F_\epsilon \left(\frac{t}{\epsilon^2}, \frac{x}{\epsilon}, v \right) dv$$

is relatively compact in $L^1_{loc}(\mathbb{R}_+ \times \mathbb{R}^3; \mathbb{R}^3)$ and each of its limit points as $\epsilon \rightarrow 0$ is a Leray solution of the Navier-Stokes equations with initial data u^{in} and viscosity

$$\nu = \frac{1}{5} \mathcal{D}^*(v \otimes v - \frac{1}{3}|v|^2 I)$$

where \mathcal{D}^* is the Legendre dual of the Dirichlet form of the collision integral.

- The Dirichlet form of the linearized collision integral is given by

$$\mathcal{D}(\Phi) = \frac{1}{2} \iiint_{\mathbf{R}^3 \times \mathbf{R}^3 \times \mathbf{S}^2} |\Phi + \Phi_* - \Phi' - \Phi'_*|^2 |v - v_*| M M_* dv dv_* d\sigma$$

for $\Phi \in C_c(\mathbf{R}_v^3; M_3(\mathbf{R}))$ (with $|\cdot|$ denoting the Hilbert-Schmidt norm).

- The above theorem was proved by F.G. & L. Saint-Raymond — in the case of Maxwell molecules, see F.G.-L.S-R., Invent. Math. 2004.

- REMARK: the definition of u_ϵ consists in intertwining the evolution of the Boltzmann equation with the invariance group of the Navier-Stokes equations, i.e., for each $\lambda > 0$

if $u \equiv u(t, x)$ is a solution of the Navier-Stokes equations, then

$T_\lambda u := \lambda u(\lambda^2 t, \lambda x)$ is also a solution of the Navier-Stokes equations

Sketch of the proof

- Introduce the **relative number density fluctuation** g_ϵ :

$$g_\epsilon(t, x, v) = \frac{F_\epsilon\left(\frac{t}{\epsilon^2}, \frac{x}{\epsilon}, v\right) - M(v)}{\epsilon M(v)}, \quad \text{where } M(v) = \frac{1}{(2\pi)^{3/2}} e^{-\frac{|v|^2}{2}}$$

- In terms of g_ϵ , the Boltzmann equation becomes

$$\epsilon \partial_t g_\epsilon + v \cdot \nabla_x g_\epsilon + \frac{1}{\epsilon} \mathcal{L} g_\epsilon = \mathcal{Q}(g_\epsilon, g_\epsilon)$$

where the **linearized collision operator** \mathcal{L} and \mathcal{Q} are defined by

$$\mathcal{L}g = -M^{-1}DC[M](Mg), \quad \mathcal{Q}(g, g) = \frac{1}{2}M^{-1}D^2\mathcal{C}[M](Mg, Mg)$$

Lemma. (Hilbert, Math. Ann. 1912) *The operator \mathcal{L} is self-adjoint, Fredholm, unbounded on $L^2(\mathbb{R}^3; Mdv)$ with $\ker \mathcal{L} = \text{span}\{1, v_1, v_2, v_3, |v|^2\}$*

1. Asymptotic fluctuations

- Multiplying the Boltzmann equation by ϵ and letting $\epsilon \rightarrow 0$ suggests that

$$g_\epsilon \rightarrow g \quad \text{with } \mathcal{L}g = 0$$

By Hilbert's lemma, g is an infinitesimal Maxwellian, i.e. is of the form

$$g(t, x, v) = \rho(t, x) + u(t, x) \cdot v + \frac{1}{2}\theta(t, x)(|v|^2 - 3)$$

Notice that g is parametrized by its own moments, since

$$\rho = \langle g \rangle, \quad u = \langle vg \rangle, \quad \text{and } \theta = \langle (\frac{1}{3}|v|^2 - 1)g \rangle$$

- NOTATION:

$$\langle \phi \rangle = \int_{\mathbf{R}^3} \phi(v) M(v) dv$$

2. Local conservation laws

For each F rapidly decaying at infinity (in v), the collision integral satisfies

$$\int_{\mathbf{R}^3} \mathcal{C}(F) dv = \int_{\mathbf{R}^3} v_k \mathcal{C}(F) dv = 0, \quad k = 1, 2, 3$$

- The first relation entails the continuity equation

$$\epsilon \partial_t \langle g_\epsilon \rangle + \operatorname{div}_x \langle v g_\epsilon \rangle = 0, \quad \text{and thus } \operatorname{div}_x \langle v g \rangle = \operatorname{div}_x u = 0$$

which is the **incompressibility condition** in the Navier-Stokes equations.

- The second relation together with entropy production controls entails

$$\partial_t \langle v g_\epsilon \rangle + \operatorname{div}_x (\langle v g_\epsilon \rangle \otimes \langle v g_\epsilon \rangle) - \nu \Delta_x \langle v g_\epsilon \rangle \rightarrow 0 \text{ modulo gradients}$$

which gives the **Navier-Stokes motion equation** in the limit as $\epsilon \rightarrow 0$.

3. Compactness arguments

- The DiPerna-Lions entropy inequality gives *a priori* bounds on the number density fluctuations that are **uniform in ϵ** ; therefore

$(1 + |v|^2)g_\epsilon$ is relatively compact in weak- $L^1_{loc}(\mathbf{R}_+; L^1(\mathbf{R}^3 \times \mathbf{R}^3))$

- Modulo extracting subsequences, for each $\phi = O(|v|^2)$ at infinity

$$\phi g_\epsilon \rightarrow \phi g \text{ weakly in } L^1_{loc}(\mathbf{R}_+; L^1(\mathbf{R}^3 \times \mathbf{R}^3))$$

and this justifies passing to the limit in expressions that are **linear in g_ϵ** .

- It remains to pass to the limit **in the nonlinear term**, i.e. to justify that

$$\langle v g_\epsilon \rangle \otimes \langle v g_\epsilon \rangle \rightarrow \langle v g \rangle \otimes \langle v g \rangle \text{ as } \epsilon \rightarrow 0$$

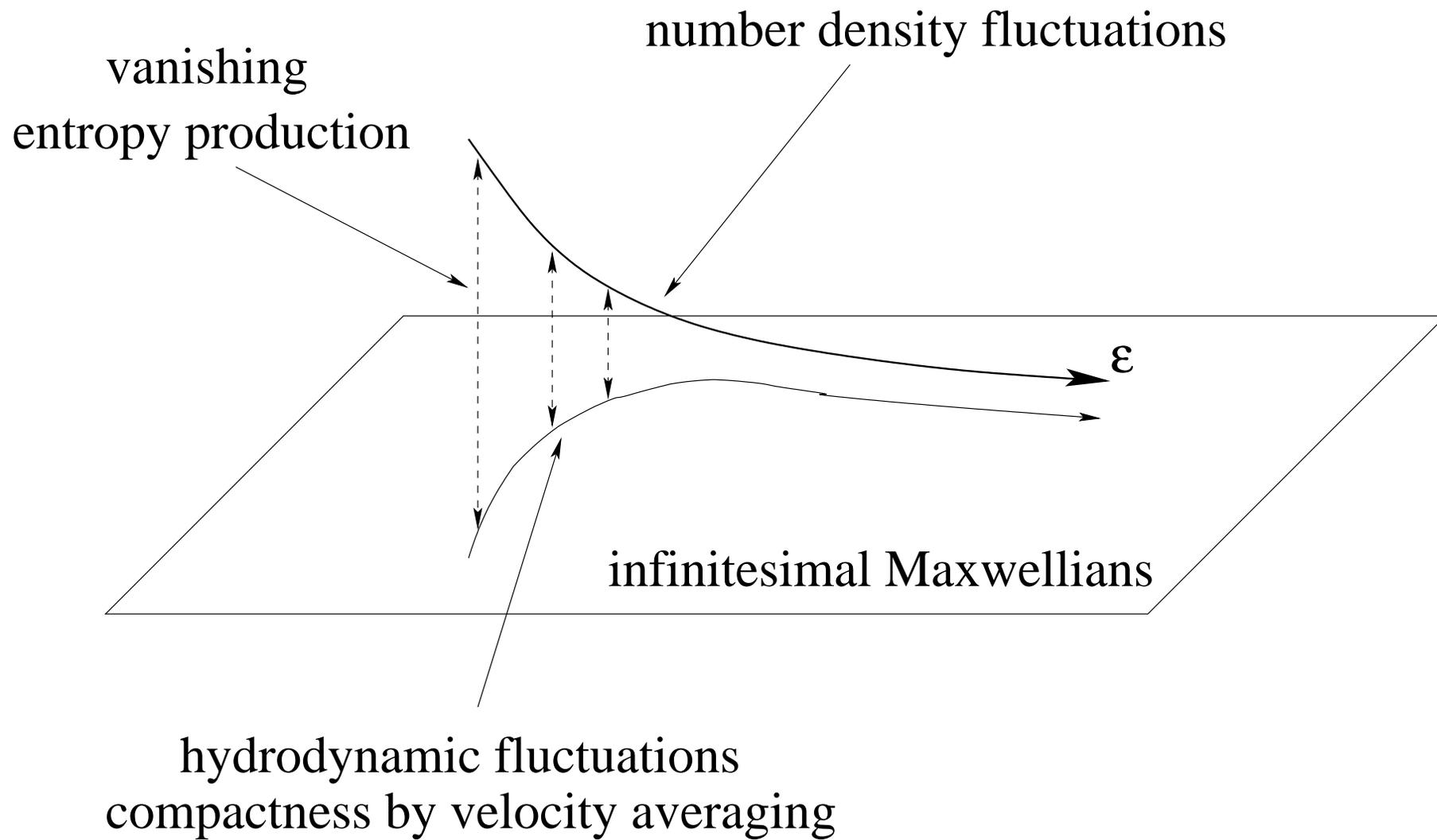
and this requires **a.e. pointwise**, instead of weak convergence.

- This is done by using a “velocity averaging” lemma, a typical example of which (in a time-independent situation) is as follows:

Lemma. (F.G.-L. Saint-Raymond, CRAS 2002) *Let $f_n \equiv f(x, v)$ be a bounded sequence in $L^1(\mathbf{R}_x^D; L^p(\mathbf{R}_v^D))$ for some $p > 1$ such that the sequence $v \cdot \nabla_x f_n$ is bounded in $L^1(\mathbf{R}^D \times \mathbf{R}^D)$. Then*

- *the sequence f_n is weakly relatively compact in $L_{loc}^1(\mathbf{R}^D \times \mathbf{R}^D)$; and*
- *for each $\phi \in C_c(\mathbf{R}^D)$, the sequence of moments*

$$\int_{\mathbf{R}^D} f_n(x, v) \phi(v) dv \text{ is strongly relatively compact in } L_{loc}^1(\mathbf{R}^D)$$



REMARKS ON VELOCITY AVERAGING:

- L^2 -variant proved with **Fourier techniques** (small divisors involving the symbol of $v \cdot \nabla_x$) by F.G.-B. Perthame-R. Sentis (CRAS 1985)
- L^2 -based **Sobolev regularity of moments** by F.G. - P.-L. Lions - B.P. - R.S. (J. Funct. Anal. 1988)
- $L^1_x(L^p_v)$ case: in **physical space** (instead of Fourier space), one sees that the group generated by $v \cdot \nabla_x$ **exchanges x - and v - regularity** for $t \neq 0$

$$e^{tv \cdot \nabla_x} \phi(x, v) = \phi(x + tv, v)$$

⇒ **dispersion estimates** “à la Strichartz”; conclude by **interpolation** using $t > 0$ as parameter.

Other limits

- From the Boltzmann equation to the Euler equations for **compressible flows**: analogous to an infinite **relaxation system** (as in Bouchut's talk)
 - a) for smooth solutions, before onset of shock waves: see Nishida (Comm. Math. Phys. 1978), and Caflisch (Comm. Pure and Appl. Math. 1980)
 - b) **acoustic** limit, under sub-optimal scaling assumptions, done by F.G. - D. Levermore (Comm. Pure Appl. Math. 2002)
 - c) **small BV** solutions in the **1D case**, “à la Glimm/Bressan”? major open problem, partial results obtained by T.P. Liu, H.S. Yu & T. Yang