

# Dynamical system on valuation space

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# The setting

$P : \mathbb{C}^2 \rightarrow \mathbb{C}^2$  polynomial

- dominant  $\Leftrightarrow P(\mathbb{C}^2) = \mathbb{C}^2 \setminus Z$ ,  $Z$  alg. curve  $\Leftrightarrow \text{Jac}(P) \not\equiv 0$
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- Describe  $\{P^n(z)\}_{n \geq 0}$  for all  $z$
- Describe  $\mathcal{B} = \{z, P^n(z) \rightarrow \infty\}$
- Speed:  $\{|P^n(z)|\}_{n \in \mathbb{N}}$

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# Plan

- 1 Introduction
- 2 Behaviour at  $\infty$  (no iteration)
- 3 Dynamical heuristic
- 4 Statements
- 5 A first approach
- 6 Action on valuation space
- 7 Next

# Basics

- $P = P_0 + P_1 + \cdots + P_d$ ,  
 $P_i : \mathbb{C}^2 \rightarrow \mathbb{C}^2$  homogeneous of degree  $i$ .
- $\|z\| := 1 + \max\{|x|, |y|\}$
- $\|P(z)\| \leq C_2 \|z\|^d$  everywhere
- $C_1 \|z\|^d \leq \|P(z)\|$  on the cone  $\Omega := \{z, |P_d(z)| \geq \varepsilon |z|^d\}$

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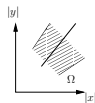
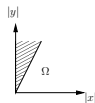
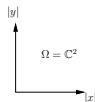
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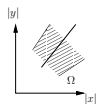
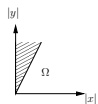
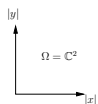
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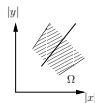
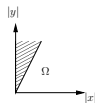
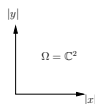
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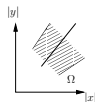
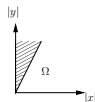
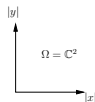
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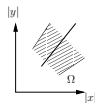
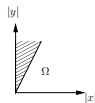
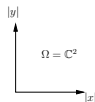
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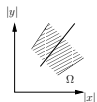
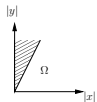
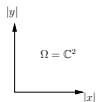
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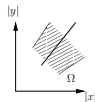
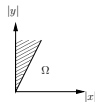
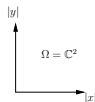
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## A few iterations

- $n$  fixed,  $d_n := \deg(P^n)$

$$C_{1,n} \|z\|^{d_n} \leq_{\text{in } \Omega_n} \|P^n(z)\| \leq_{\text{in } \mathbb{C}^2} C_{2,n} \|z\|^{d_n}.$$

- $d_{n+m} \leq d_n \times d_m$ .

### Definition (Dynamical degree)

$$d_\infty = \lim_n d_n^{1/n} \geq 1$$

### Remark

$$d_\infty(\psi^{-1} \circ P \circ \psi) = d_\infty(P), \psi : \mathbb{C}^2 \rightarrow \mathbb{C}^2 \text{ birational.}$$

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### Conjecture

- $d_n \simeq d_\infty^n$  ?
- $\Omega = \bigcap \Omega_n \neq \emptyset$  ?
- Uniform constant  $C_{1,n}, C_{2,n}$  ?

If YES, then

$$(C_1 \|z\|)^{d_\infty^n} \underset{\text{in } \Omega}{\leq} \|P^n(z)\| \underset{\text{in } \mathbb{C}^2}{\leq} (C_2 \|z\|)^{d_\infty^n} .$$

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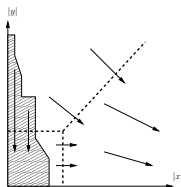
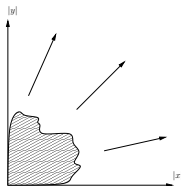
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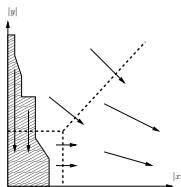
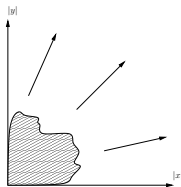
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$\mathbb{C}^2 \setminus \Omega$  compact

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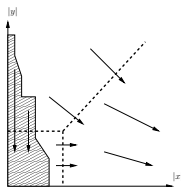
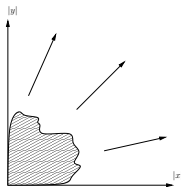
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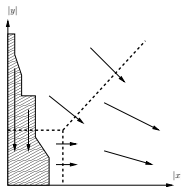
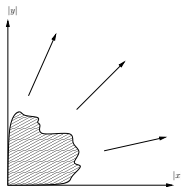
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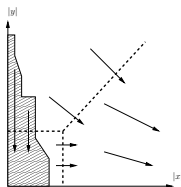
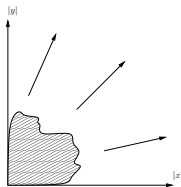
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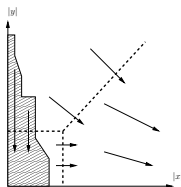
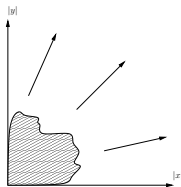
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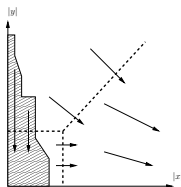
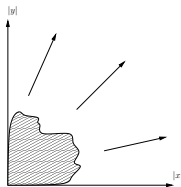
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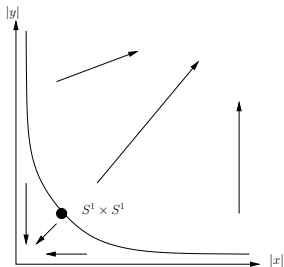
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# Monomial maps



When  $d_\infty^2 > |\det(M)|$

- $M = \begin{pmatrix} a & c \\ b & d \end{pmatrix}$

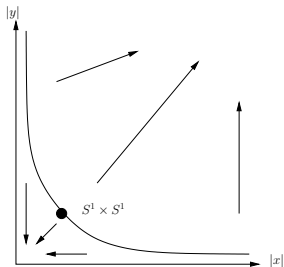
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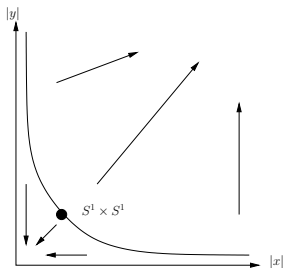
# Monomial maps



When  $d_\infty^2 > |\det(M)|$

- $M = \begin{pmatrix} a & c \\ b & d \end{pmatrix}$
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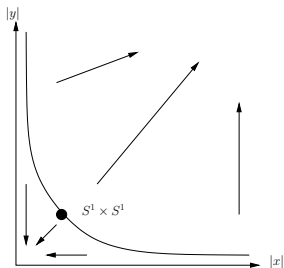
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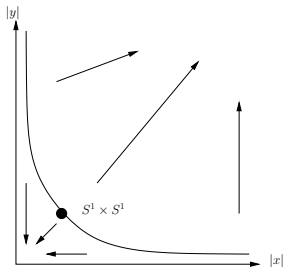
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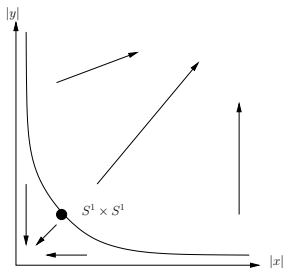
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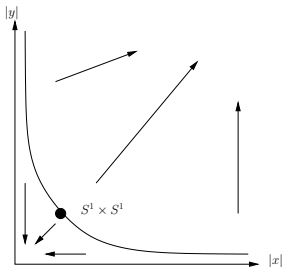
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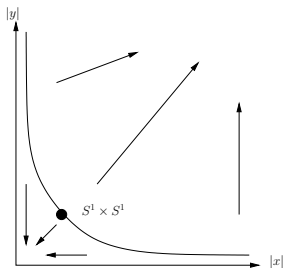
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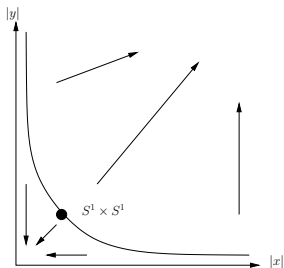
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# Skew products

## Definition

$P$  is a skew product iff it preserves a *rational* fibration of  $\mathbb{P}^2$

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- $d_\infty = \max\{k, l\}$

$$k \neq l \Rightarrow d_n \simeq d_\infty^n$$

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## Statements

### Theorem (Favre-Jonsson, 2004)

$P : \mathbb{C}^2 \rightarrow \mathbb{C}^2$  polynomial, dominant.

Then  $d_\infty^2 = ad_\infty + b$ ,  $a, b \in \mathbb{Z}$ .

- Either  $d_\infty^n \leq d_n \leq C \cdot d_\infty^n$
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### Theorem (Speed estimates)

$$g_n = \frac{1}{d_\infty^n} \log \|P^n(z)\| \longrightarrow g \neq 0 .$$

$$(g(z) - \varepsilon) d_\infty^n \lesssim \|P^n(z)\| \lesssim (g(z) + \varepsilon) d_\infty^n , \text{ on } \Omega = \{g > 0\} .$$



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- Outside  $\Omega$ , pts may tend to infinity, at different speed (Dinh-Dujardin-Sibony)
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## Sequence of degrees

Why  $d_{n+m} < d_n \times d_m$ ?

- Compactification:  $\mathbb{P}^2 = \mathbb{C}^2 \cup L_\infty$   
 $P : \mathbb{C}^2 \dashrightarrow \mathbb{C}^2$
- $P^*L_\infty = d_1L_\infty \dots (P^2)^*L_\infty \neq P^*P^*L_\infty$ ?
- $P[x : y : t] = [y^2t : x^3 : t^3]$ ,  $d_1 = 3$ ,  $d_2 = 6$   
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It works... only for birational maps! (Diller-Favre)

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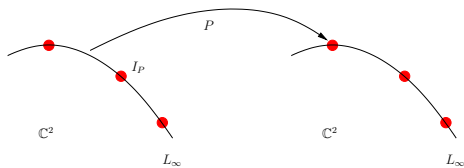
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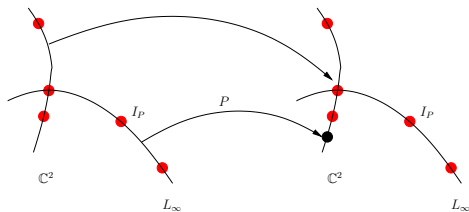
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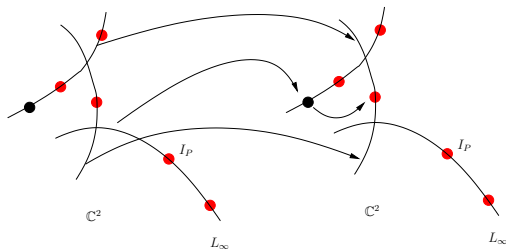
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## Conclusive remarks

Understand the dynamics of  $P$  on the set of irreducible curves  
 $C$  centered at infinity  $\pi : X \rightarrow \mathbb{P}^2$ ,  $C \subset \pi^{-1}(L_\infty)$

# Basics

- Identify  $C \rightsquigarrow \text{div}_C : \mathbb{C}[x, y] \rightarrow \mathbb{R}$   
 $L_\infty \rightsquigarrow -\text{deg}$
- $\mathcal{V}_{\text{div}} = \{\text{Divisorial valuations on } \mathbb{C}[x, y] \text{ centered at infinity}$   
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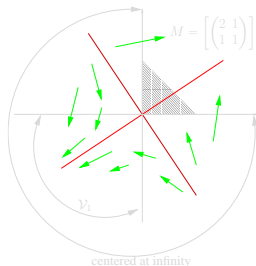
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# Monomial maps

$$P(x, y) = (x^a y^b, x^c y^d)$$

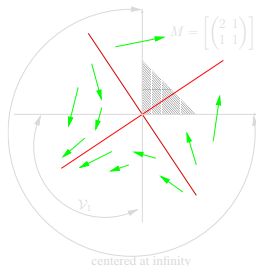
- $\nu_{s,t}$  monomial with  $\nu_{s,t}(x) = s$ ,  $\nu_{s,t}(y) = t$
- $\nu_{s,t} \in \mathcal{V}_{\text{div}} \Leftrightarrow s/t \in \mathbb{Q}$
- $\begin{pmatrix} s \\ t \end{pmatrix} \xrightarrow{P_*} \begin{pmatrix} as + bt \\ cs + dt \end{pmatrix}$



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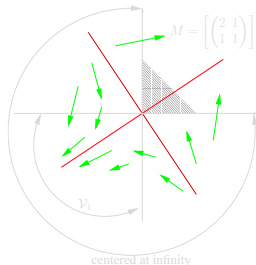
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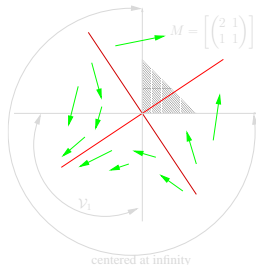
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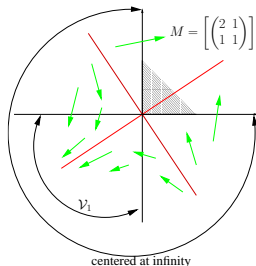
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$$\mathcal{V}_1 = \{\nu : \mathbb{C}[x, y] \rightarrow \mathbb{R}, \}$$

Fact

*Define  $P_*\nu(\phi) = \nu(\phi \circ P)$ . Then  $P_*(\mathcal{V}_1) \subset \mathcal{V}_1$*

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## Theorem (Eigenvaluation)

$P_*\nu = \lambda\nu$  for some  $\nu \in \mathcal{V}_1$

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## $\mathcal{V}_1$ is a tree

- First theorem: fixed pt theorem on tree
- Second theorem: structure result for valuation in  $\mathcal{V}_1$   
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- 1 geometry of  $\mathcal{V}_1$
- 2 global results for valuations in  $\mathcal{V}_1$
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